Taking linear algebra as an undergraduate, I got pretty lost when we discussed the Jordan Normal Form. As such, I recently needed to revisit this topic before I could understand certain results about Lie algebras. This note presented a much cleaner explanation than the other sources that I had looked at, which inspired me to jot down this framework (with a few tweaks befitting my own understanding) into a hastily written set of exercises on the topic. Several of the exercises are equipped with a footnote containing a hint.

## Generalized Eigenspaces

Let $A: V \rightarrow V$ be a linear operator on a finite-dimensional vector space over $\mathbb{C}$.
Definition. For any $\lambda \in \mathbb{C}$, the generalized $\lambda$-eigenspace of $A$ is defined to be

$$
V_{\lambda}=\left\{v \in V:(A-\lambda I)^{k} v=0 \text { for some } k \in \mathbb{N}\right\}
$$

Any non-zero $v \in V_{\lambda}$ is called a generalized $\lambda$-eigenvector. A $\lambda$-chain of length $k$ is a sequence of non-zero vectors $v_{1}, \ldots, v_{k} \in V$ such that $(A-\lambda I) v_{i}=v_{i-1}$ for all $i=2, \ldots, k$ and $(A-\lambda I) v_{1}=0$.

1. If $v_{1}, \ldots, v_{k}$ is a $\lambda$-chain, then $\left\{v_{1}, \ldots, v_{k}\right\}$ is a linearly independent subset of $V_{\lambda} .{ }^{1}$

Jordan Normal Form Theorem. There is a basis of $V$ that is a union of chains. The number of $\lambda$-chains of length $k$ in this basis depends only on our original operator $A$.

To prove this theorem, we first want to break up $V$ into its generalized eigenspaces.
2. There is some $k \in \mathbb{N}$, such that $(A-\lambda I)^{k} v=0$ for all $v \in V_{\lambda}$ (or equivalently $\left.V_{\lambda}=\operatorname{ker}(A-\lambda I)^{k}\right) .^{2}$
3. If $V_{\lambda}=\operatorname{ker}(A-\lambda I)^{k}$, then $V=\operatorname{ker}(A-\lambda I)^{k} \oplus \operatorname{im}(A-\lambda I)^{k} .{ }^{3}$
4. For any $k \in \mathbb{N}$, the subspaces $\operatorname{ker}(A-\lambda I)^{k}$ and $\operatorname{im}(A-\lambda I)^{k}$ are $A$-invariant. ${ }^{4}$
5. There exists an $A$-invariant subspace $W \subseteq V$ such that $V=V_{\lambda} \oplus W$. Moreover:
(a) If $\mu \neq \lambda$, then $A-\mu I$ restricts to an invertible operator on $V_{\lambda} .^{5}$
(b) If $\mu \neq \lambda$, then $V_{\mu} \subseteq W .{ }^{6}$
6. If the eigenvalues of $A$ are $\lambda_{1}, \ldots, \lambda_{n}$, then we have $V=V_{\lambda_{1}} \oplus \cdots \oplus V_{\lambda_{n}}$.

Each generalized eigenspace of $A$ is $A$-invariant, so to prove existence in the Jordan Normal Form Theorem, it now suffices to show that each $V_{\lambda}$ admits a basis that is a union of $\lambda$-chains. To prove this, we now restrict to a single $V_{\lambda}$ and set $B=A-\lambda I$. By what we have shown above, this operator $B$ has the following property:

Definition. A linear operator $B: V \rightarrow V$ is said to be nilpotent if $B^{k}=0$ for some $k \in \mathbb{N}$.

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## Nilpotence and Flags

Definition. A weak flag in a vector space $U$ is any ascending collection of subspaces, going from 0 to $U$ :

$$
0=N_{0} \subseteq N_{1} \subseteq \cdots \subseteq N_{\ell}=U
$$

Fix a finite set of vectors $\mathcal{S}=\left\{v_{1}, \ldots, v_{m}\right\} \in N_{j}$. We will say that $\mathcal{S}$ is $j$-spanning if $N_{j}=N_{j-1}+\operatorname{span}(\mathcal{S})$.
We will say that $\mathcal{S}$ is $j$-independent if the only $a_{1}, \ldots, a_{m} \in \mathbb{C}$ satisfying

$$
a_{1} v_{1}+\cdots+a_{m} v_{m} \in N_{j-1}
$$

are $a_{1}=\cdots=a_{m}=0$. If the set $\mathcal{S}$ is both $j$-spanning and $j$-independent, we will call it a $j$-basis.
7. Any $j$-independent set can be enlarged to form a $j$-basis.
8. For each $j=1, \ldots, \ell$, suppose that $\mathcal{S}_{j}$ is a $j$-basis. Then $\mathcal{S}_{1} \cup \cdots \cup \mathcal{S}_{\ell}$ is a basis of $U$.

Suppose $B: U \rightarrow U$ is a nilpotent operator with $B^{\ell}=0$. For each $i=0,1, \ldots, \ell$, we define $N_{i}=\operatorname{ker}\left(B^{i}\right)$.
9. This yields a weak flag $0=N_{0} \subseteq N_{1} \subseteq \cdots \subseteq N_{\ell}=U$ such that $B\left(N_{i}\right) \subseteq N_{i-1}$ for each $i=1, \ldots, \ell$.
10. If $\mathcal{S}$ is $j$-independent, then $B(\mathcal{S})$ is $(j-1)$-independent. ${ }^{7}$
11. There is a basis $\mathcal{S}$ of the vector space $U$, such that if $u \in \mathcal{S}$ and $B^{i} u \neq 0$, then $B^{i} u \in \mathcal{S} .{ }^{8}$

We now return to the situation of a linear operator $A: V \rightarrow V$, a generalized eigenspace $V_{\lambda}$ and the nilpotent operator $B: V_{\lambda} \rightarrow V_{\lambda}$ given by $B=A-\lambda I$. We still consider the weak flag $N_{i}=\operatorname{ker}\left(B^{i}\right)$ defined above.
12. The generalized eigenspace $V_{\lambda}$ admits a basis that is a union of $\lambda$-chains of $A$.
13. Given a basis of $V_{\lambda}$ that is a union of $\lambda$-chains, the number of chains of length $k$ is $\operatorname{dim} N_{k}-\operatorname{dim} N_{k-1} .{ }^{9}$

We now have all of the pieces necessary to conclude the result of the Jordan Normal Form Theorem!

## Commuting Operators

Closely related to the Jordan Normal Form Theorem is another result, describing a decomposition of $A$ :
Jordan-Chevalley Decomposition Theorem. Given a linear operator $A: V \rightarrow V$, there is a unique way to write $A=B+D$, where $D$ is diagonalizable, $B$ is nilpotent and $B D=D B$.

Before we prove this, we need to investigate a couple of more general results about commuting operators. Consider two operators $S: U \rightarrow U$ and $T: U \rightarrow U$ that satisfy $S T=T S$.
14. If $S$ and $T$ are nilpotent, then $S+T$ is nilpotent. ${ }^{10}$

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## Jordan Normal Form via Exercises

15. The eigenspaces of $S$ are $T$-invariant.
16. Now suppose that $S$ and $T$ are diagonalizable and let $U=U_{\mu_{1}} \oplus \cdots \oplus U_{\mu_{m}}$ be the decomposition into eigenspaces of $S$. For each $i=1, \ldots, m$, let $P_{i}: U \rightarrow U_{\mu_{i}}$ be the projection map out of this direct sum.
(a) For every $i=1, \ldots, m$, we have $T P_{i}=P_{i} T .{ }^{11}$
(b) If $u \in U$ is an eigenvector of $T$, then $P_{i} u$ is a common eigenvector of $S$ and $T$.
(c) Every eigenvector of $T$ can be written as a sum of common eigenvectors of $S$ and $T$.
(d) The vector space $U$ is spanned by common eigenvectors of $S$ and $T$.
(e) There is a basis for $U$ in which both $S$ and $T$ are diagonal.

This proves that if $S$ and $T$ are diagonalizable, then so is $S+T$ (under the assumption $S T=T S$ ).

Recall the decomposition $V=V_{\lambda_{1}} \oplus \cdots \oplus V_{\lambda_{n}}$ into generalized eigenspaces of $A$. We define a diagonalizable linear operator $D: V \rightarrow V$ by requiring that $D=\lambda I$ when restricted to the generalized eigenspace $V_{\lambda}$.
17. If a linear operator $B: V \rightarrow V$ commutes with $A$, then it commutes with $D .{ }^{12}$
18. The operator $B=A-D$ is nilpotent and $B D=D B \cdot{ }^{13}$

This proves existence of a Jordan-Chevalley decomposition, but we also need to show uniqueness. As such, suppose that we also have $A=B^{\prime}+D^{\prime}$, where $D^{\prime}$ is diagonalizable, $B^{\prime}$ is nilpotent and $B^{\prime} D^{\prime}=D^{\prime} B^{\prime}$.
19. The operators $B, D, B^{\prime}$ and $D^{\prime}$ all commute with each other. ${ }^{14}$
20. We have $B-B^{\prime}=D^{\prime}-D=0$, so the decomposition is unique. ${ }^{15}$

This concludes the proof of the Jordan-Chevalley Decomposition Theorem!

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[^0]:    ${ }^{1}$ If $a_{j} v_{j}+\cdots+a_{1} v_{1}=0$, what happens when you apply $(A-\lambda I)^{j-1}$ to this linear combination?
    ${ }^{2}$ If $v_{1}, \ldots, v_{n}$ is a basis of $V_{\lambda}$, then there exist $k_{1}, \ldots, k_{n} \in \mathbb{N}$ such that $(A-\lambda I)^{k_{i}} v_{i}=0$ for each $i=1, \ldots, n$.
    ${ }^{3}$ First show that their intersection is trivial.
    ${ }^{4}$ Notice that $A$ and $A-\lambda I$ commute.
    ${ }^{5}$ If $v \in \operatorname{ker}(A-\mu I)$, then $v$ is $\mu$-eigenvector of $A$. What can we conclude about $(A-\lambda I) v$ ? What about $(A-\lambda I)^{k} v$ ?
    ${ }^{6}$ Any $u \in V_{\mu}$ can be written as $u=v+w$, with $v \in V_{\lambda}$ and $w \in W$. What happens if we apply $(A-\mu I)^{k}$ to each side?

[^1]:    ${ }^{7}$ If $a_{1} B v_{1}+\cdots+a_{m} B v_{m} \in N_{j-2}$, then $a_{1} v_{1}+\cdots+a_{m} v_{m} \in N_{j-1}$.
    ${ }^{8}$ Given a $j$-basis $\mathcal{S}_{j}$, we can enlarge $B\left(\mathcal{S}_{j}\right)$ to a $(j-1)$-basis. Start with an $\ell$-basis and iterate this process.
    ${ }^{9}$ If $n_{k}$ is the number of chains of length $k$, then we have $\operatorname{dim} N_{j}=n_{j}+n_{j+1}+\cdots+n_{\ell}$ for each $j=1, \ldots, \ell$.
    ${ }^{10}$ If $S^{n}=0$ and $T^{n}=0$, then $(S+T)^{2 n}=0$.

[^2]:    ${ }^{11}$ It suffices to show that $T P_{i} u=P_{i} T u$ when $u \in U_{j}$, for each $j=1, \ldots, n$. If $u \in U_{j}$ and $i \neq j$, then $P_{i} u=0$.
    ${ }^{12}$ If $A B=B A$, then each $V_{\lambda}$ is $B$-invariant.
    ${ }^{13}$ Verify nilpotency on each $V_{\lambda}$ individually.
    ${ }^{14}$ First show that $D$ commutes with $B^{\prime}$ and $D^{\prime}$.
    ${ }^{15}$ The only operator that is both diagonalizable and nilpotent is 0 .

