# TOPOLOGICAL STABILITY OF RELATIVELY HYPERBOLIC GROUPS ACTING ON THEIR BOUNDARIES 

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#### Abstract

We prove a topological stability result for the actions of hyperbolic groups on their Bowditch boundaries. More precisely, we show that a sufficiently small perturbation of the standard boundary action, if assumed on each parabolic subgroup to be a perturbation by semi-conjugacy, is in fact always globally semi-conjugate to the standard action. This proves a relative version of the main result of MMW22]. The assumption of control on the perturbation of parabolics is necessary.


## 1. Introduction

The study of stability of boundary actions in the presence of some hyperbolicity has a long history. Sullivan Sul85 proved that the action of a Kleinian group on its limit set is stable in the sense of $C^{1}$ dynamics, meaning that $C^{1}$-close actions remain conjugate. This was generalized by Kapovich-Kim-Lee KKL to the broader class of what they call "meandering hyperbolic actions" under Lipschitz-close perturbations, examples that include the boundary actions of hyperbolic groups and of uniform lattices. More recent work has treated the more general question of topological or $C^{0}$ stability. An action $\rho_{0}$ of a group $\Gamma$ on a topological space $X$ is said to be $C^{0}$ stable if any action $\rho$ sufficiently close to $\rho_{0}$ in $\operatorname{Hom}(\Gamma, \operatorname{Homeo}(X))$ has $\rho_{0}$ as a topological factor, i.e. there exists a continuous, surjective map $h: X \rightarrow X$ such that $h \rho(\gamma)=\rho_{0}(\gamma) h$ for all $\gamma \in \Gamma$. The map $h$ is called a semi-conjugacy. This is sometimes strengthened to require that $h$ can be taken arbitrarily close to the identity map $X \rightarrow X$ by controlling how close $\rho$ is to $\rho_{0}$.

Topological stability of hyperbolic groups acting on their boundaries was shown in [BM22, MM23, MMW22; see also [Gro87]. The approach from [BM22] was very recently adapted (with much additional work) to establish topological stability for actions of uniform lattices on Furstenburg boundaries in CINS23. The current paper treats the case of boundary actions of relatively hyperbolic groups. We prove the following.

Theorem 1.1 (Stability for relatively hyperbolic groups). Let $\Gamma$ be hyperbolic relative to $\mathcal{P}$ and $\rho_{0}$ the natural action of $\Gamma$ on the Bowditch boundary $\partial(\Gamma, \mathcal{P})$.

For any neighborhood $\mathcal{V}$ of the identity in $C(\partial(\Gamma, \mathcal{P}))$, there exists a neighborhood $\mathcal{U}$ of $\rho_{0}$ in $\operatorname{Hom}(\Gamma, \operatorname{Homeo}(\partial(\Gamma, \mathcal{P})))$ and a neighborhood $\mathcal{V}^{\prime}$ of the identity in $C(\partial(\Gamma, \mathcal{P}))$ such that, if $\rho \in \mathcal{U}$ is an action whose restriction to each $P \in \mathcal{P}$ is an extension of $\rho_{0}$ via a semi-conjugacy in $\mathcal{V}^{\prime}$, then $\rho$ is an extension of $\rho_{0}$ by a semi-conjugacy in $\mathcal{V}$.
Examples. Control on the restriction of $\rho$ to each subgroup $P \in \mathcal{P}$ is necessary. In fact it is necessary even when $\Gamma$ is a lattice in a Lie group $G$, and the deformed action $\rho$ is induced by deforming the inclusion representation in the character variety.

Example 1.2. Consider a finite-area hyperbolic surface with a single cusp, isometric to a quotient $\mathbb{H}^{2} / \Gamma$ for a discrete subgroup $\Gamma \subset \operatorname{PSL}(2, \mathbb{R})$. Then $\Gamma$ is a relatively hyperbolic group, relative to the fundamental group of the cusp, and the action of this group on its Bowditch boundary is the action of $\Gamma$ on $\mathbb{R P}^{1}=\partial \mathbb{H}^{2}$.
(i) Let $\rho: \Gamma \rightarrow \operatorname{PSL}(2, \mathbb{R})$ be a small deformation of the inclusion representation $\rho_{0}: \Gamma \hookrightarrow \operatorname{PSL}(2, \mathbb{R})$ for which a generator of the cusp group acts by an elliptic transformation. As elliptic transformations have no fixed points in $\partial \mathbb{H}^{2}$, this deformed action cannot be semi-conjugate to the original boundary action.
(ii) Now let $\rho: \Gamma \rightarrow \operatorname{PSL}(2, \mathbb{R})$ be a deformation of $\rho_{0}$ where the cusp group instead acts by a loxodromic transformation, which fixes a pair of points in $\partial \mathbb{H}^{2}$ close to the parabolic fixed point for the original cusp group action. The map $\partial \mathbb{H}^{2} \rightarrow \partial \mathbb{H}^{2}$ which collapses the small arc $A$ joining this pair of fixed points is a semi-conjugacy for the $\rho$-action of the cusp group, which is close to the identity. Additionally collapsing all of the arcs in the $\rho(\Gamma)$-orbit of $A$ yields a semi-conjugacy for the $\rho$-action of the whole group $\Gamma$. This is an example of the situation described by Theorem 1.1

It is actually possible to generalize both of the examples above to higher dimensions.

Example 1.3. Suppose that $M$ is a finite-volume non-compact hyperbolic $n$ manifold, isometric to $\mathbb{H}^{n} / \Gamma$ for a discrete group $\Gamma \subset \operatorname{Isom}\left(\mathbb{H}^{n}\right) \simeq \operatorname{PO}(n, 1)$; as in the previous example, $\Gamma$ is then relatively hyperbolic, relative to its collection of cusp subgroups, and the action on its Bowditch boundary is the induced action on $\partial \mathbb{H}^{n} \simeq S^{n-1}$.
(i) When $n=3$, Thurston's hyperbolic Dehn filling theorem implies that there are arbitrarily small deformations of the inclusion $\rho_{0}: \Gamma \hookrightarrow \mathrm{PO}(n, 1)$ for which the action on $\mathbb{H}^{3}$ (and hence the induced action on $\partial \mathbb{H}^{3}$ ) has infinite kernel. These deformations cannot be semi-conjugate to the original action, where the kernel is trivial.
(ii) For each $n \geq 2$, there are examples of (non-uniform) lattices $\Gamma<P O(n, 1)$ which have deformations in $\operatorname{Hom}(\Gamma, \operatorname{PGL}(n+1, \mathbb{R}))$ which are discrete, faithful, and preserve a convex open subset $\Omega \subset \mathbb{R} \mathrm{P}^{n}$, arbitrarily close (but not equivalent) to the projective model for $\mathbb{H}^{n}$, and in some examples, the cusp groups preserve small $k$-simplices embedded in $\partial \Omega$, for some $1 \leq k<n$ (see [BDL18, BM20, Bob19]). The induced action of $\Gamma$ on $\partial \Omega \simeq S^{n-1}$ then cannot be conjugate to the original action of $\Gamma$ on $\partial \mathbb{H}^{n}$. However, it follows from Wei23, Section 5] that (for sufficiently small deformations) the map collapsing all of the $k$-simplices is a semi-conjugacy to the standard action of $\Gamma$ on its Bowditch boundary.
We also note that, in the broad context of $C^{0}$ deformations covered by Theorem 1.1 even if the restriction of $\rho$ to each peripheral subgroup is actually conjugate to the restriction of $\rho_{0}$, then $\rho$-action of the full group $\Gamma$ does not need to be conjugate to $\rho_{0}$. This can occur even when $\Gamma$ is hyperbolic and $\mathcal{P}=\emptyset$; for examples see [BM22, Section 4] and [MMW22, Example 1.4].

Outline. The broad strategy of this work follows that of MMW22, but much additional technical work is needed in the presence of parabolic elements. We adapt
and use tools and ideas from Wei22 and the geometry of relatively hyperbolic groups. A reader looking for a gentler introduction to rigidity of boundary actions may wish to first read the simpler proof in MMW22.

In Section 2 we review necessary material on relatively hyperbolic groups and set the stage for the proof. In Section 3 we define an automaton which codes boundary points, adapted to the setting of the desired stability theorem for relatively hyperbolic groups. Essential properties of this automaton are proved in Section 4

Section 5 is the technical heart of the paper. The key proposition (Proposition 5.2 is a "uniform nesting" condition for sequences of nested sets furnished by the automaton, which can be translated into a stable condition under perturbation that allows us to define the desired semi-conjugacy between the standard boundary action and a sufficiently small perturbation. Section 6 uses all the previous work to define this semi-conjugacy and conclude the proof.

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## 2. Set-up

We assume the reader has basic familiarity with the theory of relatively hyperbolic groups; general background can be found in Bow12, or GM08, Section 2] and references therein. In this section we set notation and recall the essential properties that we will use.

Let $\Gamma$ be a relatively hyperbolic group, relative to a finite collection $\mathcal{P}$ of infinite subgroups. Fix a finite, symmetric generating set $\mathcal{S}$ for $\Gamma$. We let $\operatorname{Cay}(\Gamma)=$ $\operatorname{Cay}(\Gamma, \mathcal{S})$ denote the Cayley graph of $\Gamma$ with respect to the generating set $\mathcal{S}$, and we let $d_{\Gamma}$ denote the metric on $\operatorname{Cay}(\Gamma)$ induced by this generating set. We also assume the generating set $\mathcal{S}$ is compatible with $\mathcal{P}$, i.e. that for every parabolic subgroup $P \in \mathcal{P}$, the intersection $P \cap \mathcal{S}$ is a generating set for $P$. If $\Gamma$ is hyperbolic (i.e. $\mathcal{P}=\emptyset$ ) then Theorem 1.1 follows from MMW22, so we assume for the duration of this work that $\mathcal{P} \neq \emptyset$. We also assume that $(\Gamma, \mathcal{P})$ is non-elementary (meaning that $\mathcal{P} \neq\{\Gamma\}$ and $\Gamma$ is not finite or virtually cyclic), since in these cases the Bowditch boundary $\partial(\Gamma, \mathcal{P})$ contains at most two points and the theorem is trivial.

The Bowditch boundary $\partial(\Gamma, \mathcal{P})$ can be identified with the Gromov boundary of a hyperbolic space $X=X(\Gamma, \mathcal{P}, \mathcal{S})$ which was defined in GM08 and called a cusped space for the pair $(\Gamma, \mathcal{P})$. The space $X$ is a locally finite metric graph, with each edge having length 1 . We use $d_{X}$ to refer to the metric on $X$. The group $\Gamma$ acts properly by isometries on $X$, and the Cayley graph $\operatorname{Cay}(\Gamma, \mathcal{S})$ embeds properly and $\Gamma$-equivariantly (though not quasi-isometrically) as a subgraph of $X$.

We will need to use some results on the geometry of horoballs in $X$ and geodesics near horoballs, especially in Section 5. To this end, define the depth $D_{X}$ of a vertex of $X$ to be its distance from the Cayley graph in $X$ and extend linearly across edges to get a continuous function $D_{X}: X \rightarrow[0, \infty)$. Thus, the Cayley graph in $X$ is the set $D_{X}^{-1}(0)$; a horoball is the smallest full subgraph containing the closure of a component of $D_{X}^{-1}(0, \infty)$. For an integer $k>0$, we refer to a component of $D_{X}^{-1}[k, \infty)$ as a $k$-horoball. If $\mathcal{H}$ is a horoball, we say that a geodesic $\gamma:[a, b] \rightarrow \mathcal{H}$
is regular if there are $a \leq A<B \leq b$ with $B-A \leq 3$ and

$$
\frac{d}{d t} D_{X} \circ \gamma(t)= \begin{cases}1 & t<A \\ 0 & A<t<B \\ -1 & t>B\end{cases}
$$

A geodesic in a horoball is vertical if it is regular and either $a=A=B$ or $A=B=b$. We will say a geodesic in $X$ is regular if every intersection with a horoball is regular. Whenever necessary, we will assume our geodesics are regular. We also fix an integer $\delta \geq 1$ so that the cusped space $X$ is $\delta$-hyperbolic (in the sense that all geodesic triangles are $\delta$-thin).

The following result was proved in GM08.
Lemma 2.1. GM08, Lemmas 3.10, 3.26] For any $k \geq \delta+1$, the $k$-horoballs are convex. Moreover, any geodesic in a horoball is Hausdorff distance at most 4 from a regular unit speed geodesic $\gamma:[a, b] \rightarrow X$ with the same endpoints.

We also need one more lemma about the geometry of geodesics which pass through horoballs.

Lemma 2.2. Let $\mathcal{H}$ be a $k$-horoball of $X$ for some $k \geq 0$, let $\sigma:[a, b] \rightarrow X$ be a regular unit speed geodesic, and let $\left[a^{\prime}, b^{\prime}\right]$ be a connected component of $\sigma^{-1}(\mathcal{H})$. Assume that $b^{\prime}-a^{\prime} \geq(4 \delta+3)$. Then for $t \in\left[a, a^{\prime}\right]$ we have

$$
\left(a^{\prime}-t\right)-\delta \leq d_{X}(\sigma(t), \mathcal{H}) \leq a^{\prime}-t
$$

Proof. Let $x$ be a closest point in $\mathcal{H}$ to $\sigma(t)$, and let $y=\sigma\left(a^{\prime}\right)$. Any geodesic from $\sigma(t)$ to $x$ can be extended by a vertical path to a point $x^{\prime}$ on the $k+2 \delta$-horoball $\mathcal{H}^{\prime}$ nested inside $\mathcal{H}$. Call this extended geodesic $\tau$. Now consider a geodesic triangle two of whose sides are $\tau$ and $\sigma\left(t, a^{\prime}+2 \delta\right)$. (Regularity of $\sigma$ implies that $\sigma\left(a^{\prime}+2 \delta\right)$ is on the boundary of $\mathcal{H}^{\prime}$.) The third side of the triangle has endpoints in $\mathcal{H}^{\prime}$, which is convex by the first part of Lemma 2.1. In particular the distance from $y$ to this third side is at least $2 \delta$, so there is a point $y^{\prime}$ on $\sigma(t, a+2 \delta)$ which is within $\delta$ of $y$. Either $y^{\prime}$ lies between $\sigma(t)$ and $x$, or on $\tau \cap \mathcal{H}$ at depth at most $\delta$. In either case, we deduce that $a^{\prime}-t \leq d_{X}(\sigma(t), x)+\delta$, as desired.

The Gromov boundary of the cusped space $X$ is the Bowditch boundary $\partial(\Gamma, \mathcal{P})$ of the pair $(\Gamma, \mathcal{P})$ (see Bow12], GM08). We fix a metric $d_{\partial}$ on $\partial(\Gamma, \mathcal{P})$. Metric notions such as diameter, $\epsilon$-neighborhoods are always with respect to this metric. We write $B_{r}(x)$ for the (open) ball about $x$ of radius $r$, and $N_{r}(Y)$ for the open $r$-neighborhood of a subset $Y$.

When we need to distinguish the natural action of $\Gamma$ on $\partial(\Gamma, \mathcal{P})$ from another action of this group on the space, we will use the notation $\rho_{0}(g)(x)$ for the action of $g \in \Gamma$ on $x \in \partial(\Gamma, \mathcal{P})$. However, in the first part of this work we use only this action, and so for convenience shorten this to $g x$.

Each subgroup in $\mathcal{P}$ acts on $\partial(\Gamma, \mathcal{P})$ with a unique fixed point. We denote the finite set of fixed points of groups in $\mathcal{P}$ by $\Pi$, and for $p \in \Pi$, we let $\Gamma_{p} \in P$ denote the subgroup fixing $p$. Thus,

$$
\mathcal{P}=\left\{\Gamma_{p}: p \in \Pi\right\}
$$

Any $\Gamma$-translate in $\partial(\Gamma, \mathcal{P})$ of a point in $\Pi$ is called a parabolic point.
We now recall some important properties of the action of $\Gamma$ on $\partial(\Gamma, \mathcal{P})$, which we use to set up the next construction. First, the group $\Gamma$ acts on $\partial(\Gamma, \mathcal{P})$ as a
convergence group (see Tuk94]), meaning that the induced action on the space of distinct triples in $\partial(\Gamma, \mathcal{P})$ is properly discontinuous.

Secondly, $\Gamma$ acts cocompactly on pairs of distinct points in the Bowditch boundary $\partial(\Gamma, \mathcal{P})$. Thus, we can set the following separation constant:

Definition 2.3. We fix a constant $D>0$ such that for any pair of distinct points $x, y \in \partial(\Gamma, \mathcal{P})$, there is some $g \in \Gamma$ such that $d_{\partial}(g x, g y)>D$.

Finally, the action of $\Gamma$ on $\partial(\Gamma, \mathcal{P})$ is geometrically finite in a dynamical sense, meaning that every non-parabolic point in $\partial(\Gamma, \mathcal{P})$ is a conical limit point, and every parabolic point is bounded.

We recall that a point $z \in \partial(\Gamma, \mathcal{P})$ is a conical limit point if there are distinct points $a, b \in \partial(\Gamma, \mathcal{P})$ and a sequence $\left(g_{i}\right)_{i \in \mathbb{N}}$ so that $g_{i} z \rightarrow b$ and $g_{i} x \rightarrow a$ uniformly on compacts in $\partial(\Gamma, \mathcal{P})-\{z\}$. A parabolic point $p$ is bounded if its stabilizer $\Gamma_{p} \subset \Gamma$ acts with compact quotient on the space $\partial(\Gamma, \mathcal{P})-\{p\}$. Thus, we define the following.

Definition 2.4. For each parabolic point $p \in \Pi$, we fix a compact set $K_{p} \subset$ $\partial(\Gamma, \mathcal{P})-\{p\}$ such that $\Gamma_{p} \cdot K_{p}=\partial(\Gamma, \mathcal{P})-\{p\}$.

For each $p$, since $K_{p}$ is compact, the distance $d_{\partial}(x, p)$ is bounded below by a positive constant. Further, since we assume $\Gamma$ is non-elementary, $\partial(\Gamma, \mathcal{P})$ is uncountable. Since $\Gamma_{p}$ is countable, $K_{p}$ must have positive diameter. So, we can also make the following definition.
Definition 2.5. We fix a constant $D_{\Pi}>0$ so that for each $p \in \Pi$, we have $D_{\Pi}<\operatorname{diam}\left(K_{p}\right)$ and $D_{\Pi}<d_{\partial}\left(K_{p}, p\right)$.

## 3. Automaton

In this section we give a version of the construction in Section 2 of MMW22 (see also Sections 5 and 6 of Wei22]). The former paper shows that every point in the Gromov boundary of a hyperbolic group has an "expanded neighborhood" which is well-adapted to the construction of an automaton which codes points. In the setting of this paper, conical points can be coded in essentially the manner of MMW22. However, parabolic fixed points need separate treatment, for which we adapt the approach in Wei22.

We start with the conical case, adapting Lemma 2.3 in MMW22 as follows.
Lemma 3.1 (Expanded neighborhoods). For any positive $\epsilon<\frac{D}{5}$ and any conical limit point $z \in \partial(\Gamma, \mathcal{P})$, there exists $\alpha_{z} \in \Gamma$ and a pair of open neighborhoods $V(z) \subset W(z)$ of $z$ so that
(1) $\operatorname{diam}(W(z)) \leq \epsilon$;
(2) $\operatorname{diam}\left(\alpha_{z}^{-1} W(z)\right)>4 \epsilon$; and
(3) $\bar{N}_{2 \epsilon}\left(\alpha_{z}^{-1} V(z)\right) \subset \alpha_{z}^{-1} W(z)$.

Proof. We choose some $\epsilon<\frac{D}{5}$ where $D$ is the constant from Definition 2.3 .
Let $z \in \partial(\Gamma, \mathcal{P})$ be is a conical limit point. Since $z$ is conical, we can find distinct points $a, b$ and a sequence of group elements $\left(g_{i}\right)_{i \in \mathbb{N}}$ so that $g_{i} z \rightarrow b$ and $g_{i} x \rightarrow a$ uniformly for all $x \neq z$. Up to post-composing all $g_{i}$ with a fixed element $g$ as in Definition 2.3 if necessary, we may assume $d_{\partial}(a, b) \geq D$. Also, since $\partial(\Gamma, \mathcal{P})$ is perfect, there is some point $a^{\prime} \neq a$ with $d_{\partial}\left(a, a^{\prime}\right)=\epsilon^{\prime}<\epsilon$.

Let $W(z)=B_{\epsilon / 2}(z)$, so Property (1) is satisfied. Let $K$ be the complement of $W(z)$ in $\partial(\Gamma, \mathcal{P})$. The set $K$ is compact and does not contain $z$, so for $i$ sufficiently large, we have $g_{i} K \subset B_{\epsilon^{\prime}}(a)$ and $g_{i} z \in B_{\epsilon}(b)$.

Fixing some such $i$, set $\alpha_{z}=g_{i}^{-1}$, and let $V(z)=\alpha_{z}\left(B_{\epsilon}(b)\right)$. Note that $B_{\epsilon}(a)$ contains $\alpha_{z}^{-1} K=\partial(\Gamma, \mathcal{P})-\alpha_{z}^{-1} W(z)$. Since $B_{\epsilon}(a)$ is disjoint from $B_{\epsilon}(b)$, we have

$$
V(z)=\alpha_{z}\left(B_{\epsilon}(b)\right) \quad \subset \quad \partial(\Gamma, \mathcal{P})-\alpha_{z}(K)=W_{z}
$$

The set $\alpha_{z}^{-1} W(z)=\partial(\Gamma, \mathcal{P})-\alpha_{z}^{-1} K$ contains both $b$ and $a^{\prime}, \operatorname{so} \operatorname{diam}\left(\alpha_{z}^{-1} W(z)\right) \geq$ $d_{\partial}\left(b, a^{\prime}\right) \geq D-\epsilon>4 \epsilon$, establishing Property (2).

Finally, since $d_{\partial}\left(b, \alpha_{z}^{-1} K\right) \geq D-\epsilon>4 \epsilon$, we have

$$
\bar{N}_{2 \epsilon}\left(\alpha_{z}^{-1} V(z)\right) \subset \bar{B}_{3 \epsilon}(b) \subset\left(\partial(\Gamma, \mathcal{P})-\alpha_{z}^{-1} K\right)=\alpha_{z}^{-1} W(z)
$$

establishing Property (3).
To treat parabolic points, we follow an argument given in Wei22; compare the lemma below to [Wei22, Lemma 6.7].

Lemma 3.2 (Parabolic points). For each point $p \in \Pi$, any $\epsilon<D_{\Pi} / 5$, and each $q=g p$, there exist open sets $\hat{V}(p) \subset \hat{W}(p) \subset \partial(\Gamma, \mathcal{P})$, neighborhoods $V(q) \subset W(q)$ of $q$ and a finite set $F_{q} \subset g \Gamma_{p}$ such that:
(1) $\operatorname{diam}(W(q)) \leq \epsilon$;
(2) $\operatorname{diam}(\hat{W}(p))>4 \epsilon$;
(3) $\bar{N}_{2 \epsilon}(\hat{V}(p)) \subset \hat{W}(p)$;
(4) $\bar{N}_{\epsilon}(\hat{W}(p))$ does not contain $p$;
(5) The set $W(q)$ is equal to $\{q\} \cup \bigcup_{\alpha \in g P-F_{q}} \alpha \hat{W}(p)$;
(6) The set $V(q)$ is equal to $\{q\} \cup \bigcup_{\alpha \in g P-F_{q}} \alpha \hat{V}(p)$.

Proof. Let $q \in \partial(\Gamma, \mathcal{P})$ be a parabolic point with $q=g p$ for $p \in \Pi$. Let $K_{p}$ be the compact set from Definition 2.4 so that $\Gamma_{p} \cdot K_{p}=\partial(\Gamma, \mathcal{P})-\{p\}$, $\operatorname{diam}\left(K_{p}\right)>D_{\Pi}$, and $d_{\partial}(x, p)>D_{\Pi}$ for every $x \in K_{p}$. We let $\hat{V}(p)=N_{\epsilon}\left(K_{p}\right)$, and we let $\hat{W}(p)=$ $N_{4 \epsilon}\left(K_{p}\right)$.

Conditions (2) and (3) above are immediate. Further, since $N_{\epsilon}(\hat{W}(p)) \subset N_{5 \epsilon}\left(K_{p}\right)$ and we assume $\epsilon<D_{\Pi} / 5$, we know that the closed neighborhood $\bar{N}_{\epsilon}(\hat{W}(p))$ does not contain $p$, so Condition (4) holds as well.

The stabilizer of a parabolic point $p \in \partial(\Gamma, \mathcal{P})$ acts properly discontinuously on $\partial(\Gamma, \mathcal{P})-\{p\}$. So, for any neighborhood $U$ of $p$ in $\partial(\Gamma, \mathcal{P})$, there is a finite set $F$ (depending on $U$ ) so that for any $\alpha \in \Gamma_{p}-F$, we have $\alpha \overline{W(p)} \subset U$. Thus, by taking $U=g^{-1} B_{\epsilon / 2}(q)$, we see that for $F_{q}=g F$, we have $\alpha \overline{\hat{W}(p)} \subset B_{\epsilon / 2}(q)$ for all $\alpha \in g \Gamma_{p}-F_{q}$.

We now define $W(q)$ and $V(q)$ exactly as stated in Conditions (5) and (6). Our choice of $F_{q}$ ensures that $W(q) \subset B_{\epsilon / 2}(q)$, so we know Condition (1) holds.

It remains to verify that $W(q)$ and $V(q)$ are open neighborhoods of $q$. For this, it is enough to show that $W(q)$ and $V(q)$ each contain an open neighborhood of $q$. However, since $g \Gamma_{p} \cdot K_{p}=\partial(\Gamma, \mathcal{P})-\{q\}$, and $\hat{V}(p)$ and $\hat{W}(p)$ both contain $K_{p}$, we know that $V(q)$ and $W(q)$ both contain the complement of the set $\bigcup_{\beta \in F_{q}} \beta K_{p}$. This set is a finite union of compact subsets not containing $q$, so its complement contains an open neighborhood of $q$.
3.1. Fixing $\varepsilon$ and the geometric automaton. The construction of the automaton depends on a pair of nested finite open covers of $\partial(\Gamma, \mathcal{P})$, coming from the sets $V(z)$ and $W(z)$ provided by Lemma 3.1 and Lemma 3.2. The covers we construct via these lemmas depend on the target neighborhood of the identity $\mathcal{V}$ needed in Theorem 1.1. Thus, we suppose now that we have been given some $\mathcal{V} \subset C(\partial(\Gamma, \mathcal{P}))$, and make the following definition.

Definition 3.3. We fix a constant $\varepsilon>0$ so that $\varepsilon$ is smaller than $\min \left(D / 5, D_{\Pi} / 5\right)$, and additionally such that every continuous self-map $\partial(\Gamma, \mathcal{P}) \rightarrow \partial(\Gamma, \mathcal{P}) \varepsilon$-close to the identity lies in $\mathcal{V}$.

For each conical limit point $z \in \partial(\Gamma, \mathcal{P})$, choose a pair of open neighborhoods $V(z)^{*} \subset W(z)$ of $z$ and an element $\alpha(z)$ as in the statement of Lemma 3.1, for our chosen $\varepsilon$. Later, we will modify the $V(z)^{*}$ slightly, hence the provisional $*$ in the notation, rather than simply calling the set $V(z)$ as in the Lemma statement.

For each parabolic point $p \in \Pi$ choose open sets $\hat{V}(p)^{*} \subset \hat{W}(p)$ as in Lemma 3.2 . again using the fixed $\varepsilon$. In addition, for each parabolic point $q \in \partial(\Gamma, \mathcal{P})$ with $q=g p$ for $p \in \Pi$, choose neighborhoods $V(q)^{*} \subset W(q)$ of $q$ and a finite set $F_{q} \subset g \Gamma_{p}$ as in the same lemma.

Let $Z \subset \partial(\Gamma, \mathcal{P})$ be a finite collection so that the sets $\left\{V(z)^{*}\right\}_{z \in Z}$ cover $\partial(\Gamma, \mathcal{P})$. We streamline notation as follows.
Notation 3.4. For each conical limit point $z \in Z$, we denote $\alpha_{z}^{-1} V(z)^{*}$ by $\hat{V}(z)^{*}$ and $\alpha_{z}^{-1}(W(z))$ by $\hat{W}(z)$. These sets will play an important role.

If $q=g p$ for $p \in \Pi$, we will define $\hat{V}(q)^{*}:=\hat{V}(p)^{*}$.
We will set up an automaton with vertex set $Z$, and edges determined by the combinatorics of the intersections these sets and labeled by certain elements of $\Gamma$. For this we use the following definition.

Definition 3.5. For each point $z \in Z$, let $L(z) \subset \Gamma$ be defined as follows.

- If $z$ is a conical limit point, then $L(z)$ is the singleton $\left\{\alpha_{z}\right\}$.
- If $z$ is a parabolic point $q=g p$ for $p \in \Pi$, then we define $L(z):=g \Gamma_{p}-F_{q}$, where $F_{q}$ is the set given by Lemma 3.2 .

Since we ultimately want to use this automaton to prove stability properties of the action of $\Gamma$ on $\partial(\Gamma, \mathcal{P})$, we need to make sure that this intersection pattern is stable. More precisely, we want to modify the sets $V(z)^{*}$ and $\hat{V}(z)^{*}$ slightly to sets $V(z)$ and $\hat{V}(z)$ which satisfy $\hat{\hat{V}(z)} \cap \overline{V(y)}=\emptyset$ if and only if $\hat{V}(z) \cap V(y)=\emptyset$.

For this we use the following lemma.
Lemma 3.6. For any $z \in Z$ and any $\eta>0$, there exists $r>0$ so that the set

$$
\bigcup_{\alpha \in L(z)} \alpha N_{r}\left(\hat{V}(z)^{*}\right)
$$

is contained in the $\eta$-neighborhood of $V(z)^{*}$.
Proof. When $z$ is a conical limit point, then $L(z)$ is a singleton $\left\{\alpha_{z}\right\}$ and $V(z)^{*}=$ $\alpha_{z} \hat{V}(z)^{*}$. Thus, $\alpha_{z} N_{r}\left(\hat{V}(z)^{*}\right) \subset N_{\eta}\left(\alpha_{z} \hat{V}(z)^{*}\right)$ holds for all sufficiently small $r$ because $\Gamma$ acts by homeomorphisms. Now assume that $z$ is parabolic point $q=g p$ for $p \in \Pi$, and $L(z)=g \Gamma_{p}-F_{q}$.

Part 4 of Lemma 3.2 ensures that we can choose $r$ small enough so that the closure of $N_{r}\left(\hat{V}(p)^{*}\right)$ does not contain $p$. Then, for a finite subset $E_{\eta} \subset g \Gamma_{p}$, every $\alpha \in g \Gamma_{p}-E_{\eta}$ satisfies $\alpha N_{r}(\hat{V}(p)) \subset B_{\eta}(q)$. As $V(q)$ contains $q$, this ensures that $\bigcup_{\alpha \in g \Gamma_{p}-E_{\eta}} N_{r}\left(\hat{V}(p)^{*}\right)$ is contained in $N_{\eta}\left(V(q)^{*}\right)$.

Since the set $E_{\eta}-F_{q}$ is finite, we can choose $r$ small enough so that $\alpha N_{r}\left(\hat{V}(p)^{*}\right)$ is contained in $N_{\eta}\left(\alpha \hat{V}(p)^{*}\right)$ for every $\alpha \in E_{\eta}-F_{q}$. Since $V(q)$ contains the union of sets $\alpha \hat{V}(p)^{*}$ for $\alpha \in g \Gamma_{p}-F_{q}$, this guarantees that the desired inclusion holds.

The following proposition collects the key properties of the combinatorics of an open cover that we will use to build the automaton.

Proposition 3.7. There exist sets $V(z) \supset V(z)^{*}$ and $\hat{V}(z) \supset \hat{V}(z)^{*}$ so that for each $z \in Z \backslash \Pi$ we have $\hat{V}(z)=\alpha_{z}^{-1} V(z)$, and for every $z \in Z$, we have:
(C1) $\operatorname{diam}(W(z))<\varepsilon$;
(C2) $\operatorname{diam}(\hat{W}(z))>4 \varepsilon$;
(C3) $\bar{N}_{2 \varepsilon}(\hat{V}(z)) \subset \hat{W}(z)$
(C4) The set $W(z)$ is equal to $\{z\} \cup \bigcup_{\alpha \in L(z)} \alpha \hat{W}(z)$;
(C5) The set $V(z)$ is equal to $\{z\} \cup \bigcup_{\alpha \in L(z)} \alpha \hat{V}(z)$ and $\overline{V(z)} \subset W(z)$.
(C6) For any pair $y, z \in Z$, we have $\overline{\hat{V}(z)} \cap \overline{V(y)}=\emptyset$ if and only if $\hat{V}(z) \cap V(y)=$ $\emptyset$.

Note that $\{V(z)\}_{z \in Z}$ is still a cover of $\partial(\Gamma, \mathcal{P})$, and the index set $Z$, elements $\alpha_{z}$, and sets $W(z), \hat{W}(z)$ and $L(z)$ remain unchanged.

Proof. That the sets $V(z)^{*}$ and $\hat{V}(z)^{*}$ already chosen satisfy conditions (C1) (C5) nearly follows from Lemma 3.1 and 3.2. For the last part of (C5) in the case of parabolic $z$ we must also use Lemma 3.6 .

We can replace each of the sets $\hat{V}(z)^{*}$ with a slightly larger set $\hat{V}(z)$, and define $V(z)=\alpha_{z}(\hat{V}(z))$ for conical $z$, and via the expression in (C5) for parabolic $z$. Lemma 3.6 tells us that we can do this so that $V(z), \hat{V}(z)$ are respectively contained in arbitrarily small neighborhoods of $V(z)^{*}$ and $\hat{V}(z)^{*}$, and property (C6) above holds for $V(z), \hat{V}(z)$.

By choosing $V(z)$ and $\hat{V}(z)$ sufficiently close to $V(z)^{*}, \hat{V}(z)^{*}$, we can ensure that all of the properties (C1) (C5) still hold after we replace $V(z)^{*}, \hat{V}(z)^{*}$ with $V(z)$, $\hat{V}(z)$. (Note that Condition(C3) is open, since it is about the closure of $N_{2 \varepsilon}(\hat{V}(z))$. In particular the condition is preserved when $\hat{V}(z)$ is enlarged slightly.)

For the rest of the paper, we fix the index set $Z$, the open cover $V(z)$, as well as open sets $\hat{V}(z), W(z), \hat{W}(z)$, and the sets $L(z)$ for each $z \in Z$, and assume that these sets satisfy properties (C1) (C6) above.

Definition 3.8 (The automaton). Let $\mathcal{G}$ be the directed graph with vertex set $Z$. For $(z, y) \in Z \times Z$, if $\hat{V}(z) \cap V(y)=\emptyset$ there are no directed edges from $z$ to $y$, and if $\hat{V}(z) \cap V(y) \neq \emptyset$, then for each $\alpha \in L(z)$ we put a directed edge from $z$ to $y$ labeled by $\alpha$. Thus, the set of edges from $z$ to $y$ is either empty or in bijective correspondence with $L(z)$. See Figure 1 and Figure 2

Note that there are infinitely many outgoing edges from $z \in Z$ if and only if $z$ is parabolic. We have constructed our automaton so that it satisfies the following key property:
Proposition 3.9. If there is an edge from $z$ to $y$ in $\mathcal{G}$ labeled by a group element $\alpha \in L(z)$, then we have the inclusions

$$
\begin{equation*}
\alpha \bar{N}_{\varepsilon}(W(y)) \subsetneq \alpha \hat{W}(z) \subset W(z) \tag{E1}
\end{equation*}
$$

Proof. If there is an edge from $z$ to $y$, then $\hat{V}(z) \cap V(y)$ is nonempty. By (C5), we have $V(y) \subset W(y)$, so $W(y) \cap \hat{V}(z)$ is nonempty. By (C3) we have $\bar{N}_{2 \varepsilon}(\hat{V}(z)) \subset$ $\hat{W}(z)$ Since $\operatorname{diam}(W(y))<\varepsilon$ by (C1), we have $\bar{N}_{\varepsilon}(W(y)) \subset \hat{W}(z)$. Moreover, since the diameter of $W(y)$ is at most $\varepsilon$, and the diameter of $\hat{W}(z)$ is at least $4 \varepsilon$ by (C2), this inclusion is proper. This proves the left-hand inclusion above.

Finally, property (C4) implies that if $\alpha \in L(z)$, then $\alpha \hat{W}(z) \subset W(z)$, which gives us the right-hand inclusion as well.


Figure 1. If $z$ is conical, and $\hat{V}_{z}$ meets $V_{y}$, then there is an edge from $z$ to $y$ labeled $\alpha_{z}$. The group element $\alpha_{z}$ may or may not fix the point $z$.

We note the following consequence of Proposition 3.9 for future use.
Remark 3.10. Consider a parabolic vertex $z=g p \in Z$, where $p \in \Pi$. If there is an edge from $z$ to another vertex $y \in Z$, by (E1) we have we have $\alpha \bar{N}_{\varepsilon}(W(y)) \subsetneq$ $\alpha \hat{W}(z) \subset W(z)$ for all $\alpha \in L(z)$, hence, for all but finitely many $\alpha \in g \Gamma_{p}$. It follows that the closed neighborhood $\bar{N}_{\varepsilon}(W(y))$ does not contain $p$.

As a consequence, for any given $\eta>0$ and any parabolic vertex $z \in Z$, if there is an edge from $z$ to $y$, then the inclusion $\alpha N_{\varepsilon}(W(y)) \subset B_{\eta}(z)$ holds for all but finitely many $\alpha \in L(z)$. In particular, by choosing $\eta$ sufficiently small, we can ensure that for all but finitely many exceptional $\alpha \in L(z)$, we have

$$
N_{\eta}\left(\alpha N_{\varepsilon}(W(y))\right) \subset W(z)
$$

Further, since the edge inclusion condition (E1) still holds for the finitely many exceptional $\alpha$, there is some $\epsilon_{z}>0$ so that for every $\alpha \in L(z)$, we have

$$
\begin{equation*}
N_{\epsilon_{z}}\left(\alpha\left(N_{\varepsilon} W(y)\right)\right) \subset W(z) . \tag{1}
\end{equation*}
$$



Figure 2. If $z$ is parabolic, and $\hat{V}_{z}$ meets $V_{y}$, then for each $\alpha_{i}$ in $L(z)$ there is an edge from $z$ to $y$ labeled $\alpha_{i}$. In general $\alpha_{i}$ may or may not fix $z$, meaning that $W_{z} \cap \alpha_{i} W_{z}$ may or may not be empty.

## 4. Properties of the $\rho_{0}$-automaton

In this section we explain how to associate points of $\partial(\Gamma, \mathcal{P})$ to edge paths in $\mathcal{G}$, called "codings." While points of $\partial(\Gamma, \mathcal{P})$ may have more than one coding, we also show that any two codings of the same point are geometrically related.

Notation 4.1. We will often need to work with both finite-length and infinitelength edge paths in the graph $\mathcal{G}$; some of our results will apply to all edge paths, while others may apply only to infinite paths or only to finite paths.

Whenever we refer to an edge path (or any other sequence) which may be either finite or infinite, we will let $I$ denote an index set for the sequence, which can be equal to either $\mathbb{N}=\{1, \ldots\}$ or $\{1, \ldots, n\}$ for some $n$, depending on context.

Definition 4.2. A strict conical $\mathcal{G}$-coding is an infinite edge path in $\mathcal{G}$. A strict parabolic $\mathcal{G}$-coding is a finite edge path terminating in a parabolic point. Note that it is possible that this edge path has length zero, in which case the coding is just a single parabolic point $z \in Z$.

We use the notation $\iota(e), \tau(e)$, and $\mathbf{L a b}(e)$ to denote (respectively) the initial vertex, terminal vertex, and label of an edge $e$ in a directed graph $\mathcal{G}$. If $\mathbf{e}=$ $\left(e_{k}\right)_{k \in I}$ is an edge path in $\mathcal{G}$, we call $\left(\tau\left(e_{k}\right)\right)_{k \in I}$ the terminal vertex sequence and $\left(\mathbf{L a b}\left(e_{k}\right)\right)_{k \in I}$ the label sequence for $\mathbf{e}$. We also define the initial vertex sequence for $\mathbf{e}$ in the same way, except that for convenience we index this sequence starting from zero (so its $k$ th term is $\iota\left(e_{k+1}\right)$ ).

Definition 4.3. For a strict conical coding $\mathbf{e}=\left(e_{k}\right)_{k \in \mathbb{N}}$ with label sequence $\left(\alpha_{k}\right)_{k \in \mathbb{N}}$, and terminal vertex sequence $\left(z_{k}\right)_{k \in \mathbb{N}}=\left(\tau\left(e_{k}\right)\right)_{k \in \mathbb{N}}$, if

$$
\zeta \in \bigcap_{k=0}^{\infty} \alpha_{1} \cdots \alpha_{k} \overline{W\left(z_{k}\right)}
$$

we say that $\mathbf{e}$ is a strict $\mathcal{G}$-coding of $\zeta$. If $\mathcal{G}$ is understood, we may omit it, and speak of a strict coding of $\zeta$.

Similarly, a strict parabolic coding with label sequence $\left(\alpha_{k}\right)_{k \in\{1, \ldots, n\}}$ is a strict $\mathcal{G}$-coding of the parabolic point $\zeta$ if

$$
\zeta=\alpha_{1} \ldots \alpha_{n} q
$$

where $q$ is the terminal point of the last edge. If $\mathcal{G}$ is understood, we may speak simply of a sequence that (strictly) codes $\zeta$.

Ultimately we want to use $\mathcal{G}$-codings of points in $\partial(\Gamma, \mathcal{P})$ to understand perturbations of the $\Gamma$-action on $\partial(\Gamma, \mathcal{P})$, so it is useful to introduce a formalism which also allows $\Gamma$ to act on the set of codings. In $[\mathrm{KKL}$, this kind of idea is referred to as "Sullivan's trick."

Definition 4.4. A generalized $\mathcal{G}$-coding is a pair $\left(g_{0}, \mathbf{e}\right)$, where $g_{0}$ is any element of $\Gamma$, and $\mathbf{e}$ is a strict $\mathcal{G}$-coding. The generalized coding $\left(g_{0}, \mathbf{e}\right)$ is conical if $\mathbf{e}$ is conical, and parabolic if $\mathbf{e}$ is parabolic.

If $\mathbf{e}$ codes a point $\xi \in \partial(\Gamma, \mathcal{P})$, then we say that $\left(g_{0}, \mathbf{e}\right)$ is a $\mathcal{G}$-coding of the point $g_{0} \xi$. We refer to the element $g_{0}$ as the initial point of the coding ( $\left.g_{0}, \mathbf{e}\right)$. Slightly abusing terminology, we also refer to the terminal vertex sequence of $\mathbf{e}$ as the terminal vertex sequence for $\left(g_{0}, \mathbf{e}\right)$, and similarly for label sequences and initial vertex sequences.

Note that any strict coding can be viewed as a generalized coding by taking the initial point $g_{0}$ to be the identity. Occasionally we will refer to generalized $\mathcal{G}$-codings as " $\mathcal{G}$-codings," or even just "codings" if $\mathcal{G}$ is understood from context.

Lemma 4.5. Every point in $\partial(\Gamma, \mathcal{P})$ has a strict $\mathcal{G}$-coding.
Proof. Fix a point $\zeta \in \partial(\Gamma, \mathcal{P})$. Since the $V(z)$ cover $\partial(\Gamma, \mathcal{P})$, we can choose $z_{0}$ so that $\zeta \in V\left(z_{0}\right)$. If $\zeta=z_{0}$ and $z_{0}$ is parabolic, we stop. The length-zero edge path consisting of the vertex $z_{0}$ is a strict parabolic coding of $\zeta$.

Otherwise, we inductively define a strict $\mathcal{G}$-coding as follows. Assume that we have already defined a (possibly empty) edge path $e_{1}, \ldots e_{n}$ starting at the point $z_{0}$ chosen in the last paragraph, and with $\tau\left(e_{k}\right)=z_{k}$ for each $k>0$. Set $\alpha_{k}=\mathbf{L a b}\left(e_{k}\right)$ and make the inductive hypothesis that

$$
\zeta_{n}:=\alpha_{n}^{-1} \cdots \alpha_{1}^{-1} \zeta \in V\left(z_{n}\right)
$$

This implies that

$$
\zeta \in \alpha_{1} \cdots \alpha_{n} W\left(z_{n}\right)
$$

There are now two possibilities. If $z_{n}$ is not a parabolic point, then we let $\alpha_{n+1}$ be the only element in the singleton set $L\left(z_{n}\right)$. Then define $\zeta_{n+1}=\alpha_{n+1}^{-1} \zeta_{n}$, which lies in $\alpha_{n+1}^{-1} V\left(z_{n}\right)=\hat{V}\left(z_{n}\right)$. Since the sets $V(z)$ cover, we can find some $z_{n+1} \in Z$ so that $\zeta_{n+1} \in V\left(z_{n+1}\right)$. Then there is an edge $e_{n+1}$ between $z_{n}$ and $z_{n+1}$ because $\hat{V}\left(z_{n}\right)$ and $V\left(z_{n+1}\right)$ have nonempty intersection.

If instead $z_{n}$ is a parabolic point, then we may have that $\zeta=\alpha_{1} \ldots \alpha_{n} z_{n}$, in which case we are done and have found a strict parabolic coding of $\zeta$. Otherwise,
by property (C5) of our open covers, there is some $\alpha_{n+1} \in L\left(z_{n}\right)$ so that $\alpha_{n+1}^{-1}\left(\zeta_{n}\right) \in$ $\hat{V}\left(z_{n}\right)$. Define $\zeta_{n+1}=\alpha_{n+1}^{-1} \zeta_{n}$, as above, pick some $z_{n+1}$ so that $\zeta_{n+1} \in V\left(z_{n+1}\right)$. There is an edge $e_{n+1}$ between $z_{n}$ and $z_{n+1}$ because $\hat{V}\left(z_{n}\right)$ and $V\left(z_{n+1}\right)$ have nonempty intersection.

Thus, if the inductive procedure terminates at a finite stage, we have produced a parabolic coding of $\zeta$. Otherwise, by construction we produce an infinite edge path with labels $\alpha_{k}$ such that $\zeta \in \bigcap_{n} \alpha_{1} \cdots \alpha_{n} \overline{W\left(z_{n}\right)}$, as desired.

It turns out that conical $\mathcal{G}$-codings actually code (unique) conical points in $\partial(\Gamma, \mathcal{P})$, although this is not obvious from the lemma above. We will prove this fact later in Corollary 4.11. We will also eventually show that conical codings determine sequences in $\Gamma$ that are well-defined up to some bounded error (Lemma 4.13).

To prove these two facts, we first show that codings define sequences of elements that stay close to geodesic rays in the cusped space $X$. We use the following basic fact about hyperbolic metric spaces. The statement is a rephrasing of Lemma 3.2 of [MMW22], and we refer the reader there for a proof.
Lemma 4.6 (See MMW22 Lemma 3.2). Let $X$ be a proper $\delta$-hyperbolic metric space, and fix a metric $d_{\partial}$ on the Gromov boundary $\partial X$ and a basepoint $x_{0} \in X$. For any $\epsilon_{0}>0$ and any $R_{1}>0$, there exists a constant $R_{2}$ satisfying the following.

Let $z_{1}, z_{2}, z_{3}$ be three points in $\partial X$, and for each $i, j$ distinct in $\{1,2,3\}$ let $\left[z_{i}, z_{j}\right]$ be a geodesic joining $z_{i}$ to $z_{j}$. If the distance between $z_{i}$ and $z_{j}$ is at least $\epsilon_{0}$ for each distinct pair $z_{i}, z_{j}$, then the intersection

$$
N_{R_{1}}\left(\left[z_{1}, z_{2}\right]\right) \cap N_{R_{1}}\left(\left[z_{1}, z_{3}\right]\right)
$$

is contained in the $R_{2}$-neighborhood of a geodesic ray from $x_{0}$ to $z_{1}$.
Now, using the strategy of Lemma 3.4 in MMW22, we show the following.
Lemma 4.7. There exists a uniform constant $R>0$ so that, for any strict coding e of any point $\zeta \in \partial(\Gamma, \mathcal{P})$, if $\left(\alpha_{k}\right)_{k \in I}$ is the associated label sequence, then the sequence

$$
g_{k}:=\alpha_{1} \cdots \alpha_{k}
$$

lies in the $R$-neighborhood of any geodesic ray in the cusped space $X$ based at the identity in $\operatorname{Cay}(\Gamma) \subset X$ and with endpoint $\zeta \in \partial X=\partial(\Gamma, \mathcal{P})$.

Proof. Let $\epsilon_{0}>0$ be small enough so that $\epsilon_{0}<\varepsilon$, and so that for every $z \in \partial(\Gamma, \mathcal{P})$, there exist points $z_{+}, z_{-} \in \partial(\Gamma, \mathcal{P})$ so that

$$
d_{\partial}\left(z, z_{ \pm}\right)>\varepsilon, \quad d_{\partial}\left(z_{+}, z_{-}\right)>\epsilon_{0}
$$

That such an $\epsilon_{0}$ exists follows from an easy geometric argument using the fact that $\varepsilon<D / 5$ (recall $D$ is the constant from Definition 2.3); see Lemma 3.1 in MMW22 for a proof. We also choose a constant $R_{1}>0$ so that, for any pair of points $a, b \in \partial(\Gamma, \mathcal{P})$ such that $d_{\partial}(a, b) \geq \varepsilon$, any geodesic in $X$ joining $a$ to $b$ passes within an $R_{1}$-neighborhood of the identity.

Now fix $\zeta \in \partial(\Gamma, \mathcal{P})$, and let $\mathbf{e}$ be a strict $\mathcal{G}$-coding for $\zeta$, with label sequence $\left(\alpha_{k}\right)_{k \in I}$ and terminal vertex sequence $\left(z_{k}\right)_{k \in I}$. We define $z_{0}$ to be the initial vertex of the coding, and let $g_{k}:=\alpha_{1} \cdots \alpha_{k}$. For all $k \in I \cup\{0\}$, we write $W_{k}$ for $W\left(z_{k}\right)$. Since $\mathbf{e}$ is a coding for $\zeta$ we know $\zeta \in W_{0}$.

Choose points $\zeta_{ \pm} \in \partial(\Gamma, \mathcal{P})$ so that $d_{\partial}\left(\zeta, \zeta_{-}\right)>\varepsilon, d_{\partial}\left(\zeta_{,} \zeta_{+}\right)>\varepsilon$, and $d_{\partial}\left(\zeta_{-}, \zeta_{+}\right)>$ $\epsilon_{0}$. Condition (C1) implies that the diameter of $W_{0}$ is less than $\varepsilon$, so we know that
$\zeta_{+}$and $\zeta_{-}$both lie in $\partial(\Gamma, \mathcal{P})-W_{0}$. Let $\left[\zeta_{-}, \zeta\right]$ be a geodesic in $X$ from $\zeta_{-}$to $\zeta$ and $\left[\zeta_{+}, \zeta\right]$ a geodesic from $\zeta_{+}$to $\zeta$.

The edge inclusion condition E1), together with the fact that $\mathbf{e}$ is a strict coding for $\zeta$, implies that $g_{k}^{-1} \zeta \in W_{k}$ and $g_{k} N_{\varepsilon}\left(W_{k}\right) \subset W_{0}$ for every $k$. Thus $g_{k}^{-1}(\partial(\Gamma, \mathcal{P})-$ $\left.W_{0}\right)$ is a subset of $\partial(\Gamma, \mathcal{P})-N_{\varepsilon}\left(W_{k}\right)$, so $g_{k}^{-1} \zeta_{-}$lies in $\partial(\Gamma, \mathcal{P})-N_{\varepsilon}\left(W_{k}\right)$ and therefore $d_{\partial}\left(g_{k}^{-1} \zeta_{-}, g_{k}^{-1} \zeta\right) \geq \varepsilon$.

Thus, by our choice of $R_{1}$, the geodesic $g_{k}^{-1}\left[\zeta_{-}, \zeta\right]$ enters an $R_{1}$-neighborhood of the identity. Equivalently, $g_{k}$ lies in the $R_{1}$-neighborhood of the geodesic $\left[\zeta_{-}, \zeta\right]$. The same argument also shows that $g_{k}$ lies in an $R_{1}$-neighborhood of the geodesic $\left[\zeta_{+}, \zeta\right]$. Now apply Lemma 4.6 with $z_{1}=\zeta, z_{2}=\zeta_{-}$, and $z_{3}=\zeta_{+}$to see that there is a constant $R_{2}$ (independent of $\zeta$ and $\mathbf{e}$ ) so that $g_{k}$ lies in the $R_{2}$-neighborhood of some geodesic ray from the identity to $\zeta$. Setting $R=R_{2}+2 \delta$, we conclude that all $g_{k}$ lie in the $R$-neighborhood of any such geodesic ray.

Although the previous lemma only applies directly to strict codings, we can use it to obtain a statement for generalized codings as well. Here and in what follows, we use the notation $|\alpha|_{X}$ for $d_{X}(\alpha, i d)$, where $i d$ is the image of the identity element of $\Gamma$ in $\operatorname{Cay}(\Gamma) \subset X$.

Corollary 4.8. Let $R>0$ be the constant from Lemma 4.7, and let $\left(g_{0}, \mathbf{e}\right)$ be a generalized $\mathcal{G}$-coding of a point $\zeta \in \partial(\Gamma, \mathcal{P})$, with label sequence $\left(\alpha_{k}\right)_{k \in I}$. Then the sequence

$$
g_{k}:=g_{0} \cdot \alpha_{1} \cdots \alpha_{k}
$$

lies in the $\left(R+\left|g_{0}\right|_{X}+2 \delta\right)$-neighborhood of any geodesic ray in $X$ from id to $\zeta$.
Proof. Lemma 4.7 immediately implies that the sequence $\left(g_{k}\right)_{k \in I \cup\{0\}}$ lies within an $R$-neighborhood of a geodesic $\left[g_{0}, \zeta\right]$ in $X$ from $g_{0}$ to $\zeta$. However, this geodesic lies within distance $\left|g_{0}\right|_{X}+2 \delta$ of any geodesic $[i d, \zeta]$ in $X$ from $i d$ to $\zeta$. To see this, simply make a long quadrilateral with one side a geodesic segment from $i d$ to $g_{0}$, two sides long sub-segments of the rays from $i d$ and $g_{0}$ to $\zeta$, and the fourth side a short path between these rays far from $i d$. That quadrilaterals are $2 \delta$-slim now implies that $\left[g_{0}, \zeta\right]$ lies within the $R+2 \delta$ neighborhood of $[i d, \zeta]$, and vice versa.

The sequence $\left(g_{k}\right)_{k \in I \cup\{0\}}$ from Lemma 4.7 and Corollary 4.8 will make many appearances, so we make the following definition.

Definition 4.9. If $\left(g_{0}, \mathbf{e}\right)$ is a generalized coding with label sequence $\left(\alpha_{k}\right)_{k \in I}$, we call the sequence $\left(g_{k}\right)_{k \in I \cup\{0\}}$ defined by $g_{k}:=g_{0} \cdot \alpha_{1} \cdots \alpha_{k}$ the quasi-geodesic sequence associated to $\left(g_{0}, \mathbf{e}\right)$.

The terminology "quasi-geodesic sequence" comes from the fact that $\left(g_{k}\right)_{k \in I \cup\{0\}}$ lies bounded distance from a geodesic in the cusped space $X$, and behaves like a quasi-geodesic in the relative Cayley graph for $\Gamma$ (i.e. the Cayley graph for $\Gamma$ defined with respect to the infinite generating set $\left.\mathcal{S} \cup \bigcup_{p \in \Pi} \Gamma_{p}\right)$. However, note that $\left(g_{k}\right)_{k \in I \cup\{0\}}$ may not be a quasi-geodesic in $X$, since the distances $d_{X}\left(g_{k}, g_{k+1}\right)$ may be arbitrarily large.

At this point, we have only shown (via Lemma 4.7) that the associated quasigeodesic sequence $\left(g_{k}\right)_{k \in I \cup\{0\}}$ stays in a uniform neighborhood of a geodesic ray in $X$. To see that the sequence actually follows the ray to infinity, we will use an argument from Lemma 2.11 in MMW22:

Lemma 4.10 (Bounded backtracking I). Let $\left(g_{0}, \mathbf{e}\right)$ be a generalized coding with terminal vertex sequence $\left(z_{k}\right)_{k \in I}$ and associated quasi-geodesic sequence $\left(g_{k}\right)_{k \in I \cup\{0\}}$. For every $k$, there is a proper inclusion

$$
g_{k+1} W\left(z_{k+1}\right) \subsetneq g_{k} W\left(z_{k}\right)
$$

Moreover, no element in $\left(g_{k}\right)_{k \in I \cup\{0\}}$ is repeated more than $\# Z$ times.
Proof. The first statement follows directly from Proposition 3.9. Given this, we now prove the second statement. Suppose for a contradiction that for some $g \in \Gamma$ we have $\#\left\{k: g_{k}=g\right\}>\# Z$. Then there are distinct $k, k^{\prime} \in \mathbb{N}$ such that $g_{k}=g_{k^{\prime}}=g$ and $z_{k}=z_{k^{\prime}}$. But then $g_{k} W\left(z_{k}\right)=g_{k^{\prime}} W\left(z_{k^{\prime}}\right)$, which contradicts the proper inclusion already established.

Corollary 4.11. Every conical $\mathcal{G}$-coding codes a unique conical limit point.
Proof. The statement for generalized codings follows immediately from the statement for strict codings, so fix a strict conical coding e. That some point $\zeta$ is coded by e follows immediately from Definition 4.3 . Lemma 4.7 and Lemma 4.10 imply that the point $\zeta$ is uniquely determined, because the associated quasi-geodesic sequence $\left(g_{k}\right)_{k \in \mathbb{N}}$ tends to infinity in $\Gamma$ and stays in a uniform neighbood of a geodesic ray in $X$ with ideal endpoint $\zeta$. But this is just another way of saying that $\zeta$ is a conical limit point (see e.g. BH20, Prop. A.2] for the equivalence).

Corollary 4.12 (Bounded backtracking II). Let $R$ be the constant from Lemma 4.7. Suppose $\left(g_{0}, \mathbf{e}\right)$ is a generalized conical coding with associated quasi-geodesic sequence $\left(g_{k}\right)_{k \in I \cup\{0\}}$. For any $m \in \mathbb{N}$ and any $n>m$, we have $d_{X}\left(i d, g_{n}\right)>$ $d_{X}\left(i d, g_{m}\right)-\left(3 R+2\left|g_{0}\right|_{X}+6 \delta\right)$.

Proof. Let $\zeta$ be the point coded by $\left(g_{0}, \mathbf{e}\right)$, and let $\sigma$ be a ray in $X$ from the identity to $\zeta$. By Corollary 4.8, we have $d\left(g_{k}, \sigma\right)<R+\left|g_{0}\right|_{X}+2 \delta$ for all $k$. Fix indices $m<n$, and let $x_{m}$ be a point along $\sigma$ which is within distance $R+\left|g_{0}\right|_{X}+2 \delta$ of $g_{m}$.

Consider the strict conical coding $\mathbf{e}^{\prime}$ in $\mathcal{G}$ given by the edge path $\left(e_{k+m}\right)_{k \in \mathbb{N}}$. The label sequence for this coding is the tail of the label sequence for $\mathbf{e}$, so the associated quasi-geodesic is the sequence $\left(g_{k}^{\prime}\right)_{k \in \mathbb{N}}$, where $g_{k}^{\prime}:=g_{m}^{-1} g_{k+m}$. It follows that $\mathbf{e}^{\prime}$ codes the point $g_{m}^{-1} \zeta$, hence (by Lemma 4.7) the sequence $g_{k}^{\prime}$ stays within distance $R$ of a geodesic ray $\sigma^{\prime}$ from id to $g_{m}^{-1} \zeta$.

Let $\sigma^{\prime \prime}$ be the sub-ray of $\sigma$ from $x_{m}$ to $\zeta$, so that $g_{m}^{-1} \sigma^{\prime \prime}$ is a ray from $g_{m}^{-1} x_{m}$ to $g_{m}^{-1} \zeta$. Since $d_{X}\left(x_{m}, g_{m}\right)=d_{X}\left(g_{m}^{-1} x_{m}, i d\right)<R+\left|g_{0}\right|_{X}+2 \delta$, the rays $\sigma^{\prime}$ and $g_{m}^{-1} \sigma^{\prime \prime}$ have Hausdorff distance bounded by $R+\left|g_{0}\right|_{X}+4 \delta$ (see the argument in the proof of Corollary 4.8.

Now, let $x_{n}^{\prime}$ be a point on the ray $\sigma^{\prime}$ so that $g_{n-m}^{\prime}=g_{m}^{-1} g_{n}$ lies within distance $R$ of $x_{n}^{\prime}$. There is a point $x_{n}^{\prime \prime}$ on $\sigma^{\prime \prime}$ so that $d_{X}\left(g_{m}^{-1} x_{n}^{\prime \prime}, x_{n}^{\prime}\right)<R+\left|g_{0}\right|_{X}+4 \delta$, meaning $d_{X}\left(g_{m}^{-1} g_{n}, g_{m}^{-1} x_{n}^{\prime \prime}\right)=d_{X}\left(g_{n}, x_{n}^{\prime \prime}\right) \leq 2 R+\left|g_{0}\right|_{X}+4 \delta$. Using the fact that $\sigma^{\prime \prime}$ is a sub-ray of $\sigma$ based at $x_{m}$, we have

$$
d_{X}\left(i d, g_{n}\right)+d_{X}\left(g_{n}, x_{n}^{\prime \prime}\right) \geq d_{X}\left(i d, x_{n}^{\prime \prime}\right)=d_{X}\left(i d, x_{m}\right)+d_{X}\left(x_{m}, x_{n}^{\prime \prime}\right) \geq d_{X}\left(i d, x_{m}\right)
$$

We have seen that

$$
d_{X}\left(i d, x_{m}\right) \geq d_{X}\left(i d, g_{m}\right)-\left(R+\left|g_{0}\right|_{X}+2 \delta\right)
$$

and

$$
d_{X}\left(g_{n}, x_{n}^{\prime \prime}\right) \leq 2 R+\left|g_{0}\right|_{X}+4 \delta
$$

Combining the above inequalities gives the desired bound $d_{X}\left(i d, g_{n}\right)>d_{X}\left(i d, g_{m}\right)-$ $\left(3 R+2\left|g_{0}\right|_{X}+6 \delta\right)$.

As a consequence of Corollary 4.12, whenever some edge label $\alpha_{i}$ in a generalized coding $\left(g_{0}, \mathbf{e}\right)$ satisfies $\left|\alpha_{i}\right|_{X}>3 R+2\left|g_{0}\right|_{X}+4 \delta$, the associated quasi-geodesic sequence makes positive progress along the ray it tracks. This will be important in the following section.

The final lemma of this section shows that conical codings are "unique up to bounded distance," as follows.

Lemma 4.13. For any $g_{0}, h_{0} \in \Gamma$, there exists a constant $D_{0}>0$ satisfying the following. Suppose that $\left(g_{0}, \mathbf{e}\right),\left(h_{0}, \mathbf{f}\right)$ are two generalized codings of a common conical point $\zeta$. Then the Hausdorff distance between the sets $\left\{g_{k}: k \geq 0\right\}$ and $\left\{h_{k}: k \geq 0\right\}$ (with respect to the metric $d_{X}$ ) is at most $D_{0}$.

Before proving the lemma, we fix notation for some more data related to the automaton $\mathcal{G}$ which will appear in both the proof below and in several arguments in the following section.
Definition 4.14. For each parabolic vertex $q$ of our automaton, we choose an element $t_{q} \in \Gamma$ so that $t_{q}^{-1} q \in \Pi$; we make this choice so that $\left|t_{q}\right|_{X}$ is minimized.

Then define the quantity $C$ by

$$
C=2 \delta+6+\max \left(\left\{\left|t_{q}\right|_{X}: q \in Z \text { parabolic }\right\} \cup\left\{\left|\alpha_{z}\right|_{X}: z \in Z \text { conical }\right\}\right) .
$$

Recall that when $z \in Z$ is conical, $\alpha_{z}$ is the unique element in the label set $L(z)$.
Proof of Lemma 4.13. Fix a conical point $\zeta \in \partial(\Gamma, \mathcal{P})$ and a geodesic ray $\sigma$ in $X$ from $i d$ to $\zeta$, and let $g_{0}, h_{0}$ be arbitrary elements of $\Gamma$. Consider a pair of generalized codings $\left(g_{0}, \mathbf{e}\right)$ and $\left(h_{0}, \mathbf{f}\right)$ of $\zeta$. Letting $R$ be the constant from Lemma 4.7, and defining

$$
R_{0}=R+\max \left\{\left|g_{0}\right|_{X},\left|h_{0}\right|_{X}\right\}+6 \delta,
$$

Corollary 4.8 implies that the associated quasi-geodesic sequences for both $\left(g_{0}, \mathbf{e}\right)$ and $\left(h_{0}, \mathbf{f}\right)$ lie in the set

$$
N_{R_{0}}(\sigma) \cap \operatorname{Cay}(\Gamma)
$$

Let $\left(g_{k}\right)_{k \in I \cup\{0\}}$ be the quasi-geodesic sequence associated to $\left(g_{0}, \mathbf{e}\right)$, and let $\left(e_{k}\right)_{k \in \mathbb{N}}$ and $\left(\alpha_{k}\right)_{k \in \mathbb{N}}$ be the sequence of edges and labels for $\mathbf{e}$.

Suppose that for some particular $k>0$, we have $\left|\alpha_{k}\right|_{X} \geq C$. Then $\iota\left(e_{k}\right)$ is parabolic, equal to $t_{k} p_{k}$ for some $p_{k} \in \Pi$ and $t_{k} \in \Gamma$ chosen in Definition 4.14. We thus have $\alpha_{k}=t_{k} a_{k}$ for $a_{k} \in \Gamma_{p_{k}}$, and the group elements $g_{k-1} t_{k}$ and $g_{k}=g_{k-1} t_{k} a_{k}$ lie on the boundary of a common horoball $\mathcal{H}$ in $X$. We let $\tau_{k}$ be a regular $\mathcal{H}$-geodesic joining $g_{k-1} t_{k}$ to $g_{k}$.

Let $\tau_{k}^{\prime}$ be the subsegment of $\tau_{k}$ contained in the $\delta+1$-horoball nested inside $\mathcal{H}$. Our assumption on $\left|\alpha_{k}\right|_{X}$ ensures that $\tau_{k}^{\prime}$ is non-empty. Lemma 2.1 says that $\tau_{k}^{\prime}$ is an $X$-geodesic, and the remaining subsegments of $\tau_{k}$ are vertical, so they are also $X$-geodesics. The endpoints $g_{k-1} t_{k}$ and $g_{k}$ of $\tau_{k}$ are distance at most $R_{0}+C$ from points $s_{k}$ and $s_{k+1}$ on $\sigma$. We thus obtain a geodesic hexagon, one of whose sides is a part of $\sigma$, with the opposite side equal to $\tau_{k}^{\prime}$. Any point of $\tau_{k}-\tau_{k}^{\prime}$ is at most $R_{0}+C+\delta+1$ from either $s_{k}$ or $s_{k+1}$. And any point of $\tau_{k}^{\prime}$ is within $4 \delta$ of one of the other five sides of the hexagon, hence within $R_{0}+C+5 \delta+1$ of a point of $\sigma$.

For each index $k$ such that $\left|\alpha_{k}\right|_{X} \geq C$, we fix a path $\tau_{k}$ as above. Consider the set

$$
\begin{equation*}
Y_{\mathbf{e}}=\{i d\} \cup\left\{g_{j}: j \geq 0\right\} \cup \bigcup\left\{\tau_{k}:\left|\alpha_{k}\right|_{X} \geq C\right\} \tag{2}
\end{equation*}
$$

Since each $g_{j}$ for $j \geq 0$ is contained in an $R_{0}$-neighborhood of $\sigma$, and each segment $\tau_{k}$ is contained within an $\left(R_{0}+C+5 \delta+1\right)$-neighborhood of $\sigma$, the whole set $Y_{\mathbf{e}}$ is also contained within an $\left(R_{0}+C+5 \delta+1\right)$-neighborhood of $\sigma$. We also know that the set $Y_{\mathbf{e}}$ is $\left(C+\left|g_{0}\right|_{X}\right)$-coarsely connected, since $d_{X}\left(i d, g_{0}\right)=\left|g_{0}\right|_{X}$ by definition, and for each $k>0$ either $d_{X}\left(g_{k-1}, g_{k}\right)=\left|\alpha_{k}\right|_{X}<C$ or there is a path $\tau_{k}$ in $Y_{\mathbf{e}}$ with one endpoint equal to $g_{k}$ and the other within $C$ of $g_{k-1}$.

Lemma 4.10 implies that the set of points $\left\{g_{j}: j \geq 0\right\}$ has unbounded diameter in $X$, which means that there are points of $X$ arbitrarily far along $\sigma$ that lie within distance $R_{0}+C+5 \delta+1$ of $Y_{\mathbf{e}}$. This means that $Y_{\mathbf{e}}$ is actually within Hausdorff distance $R^{\prime}$ of $\sigma$, for a constant $R^{\prime}$ depending only on $R_{0}, C, \delta$, and $\left|g_{0}\right|_{X}$.

The coding $\left(h_{0}, \mathbf{f}\right)$ has an associated set $Y_{\mathbf{f}}$ defined analogously to the way $Y_{\mathbf{e}}$ was defined above in (2). The same argument shows that the Hausdorff distance from $\sigma$ to $Y_{\mathbf{f}}$ is at most $R^{\prime \prime}$, for a constant $R^{\prime \prime}$ depending only on $R_{0}, C, \delta$, and $\left|h_{0}\right|_{X}$. Thus the Hausdorff distance between $Y_{\mathbf{e}}$ and $Y_{\mathbf{f}}$ is at most $R^{\prime}+R^{\prime \prime}$.

Now consider some $h_{k}$ in the associated quasi-geodesic sequence for $\left(h_{0}, \mathbf{f}\right)$. We wish to show that $h_{k}$ lies uniformly close to some point $g_{j}$ in the associated sequence for $\left(g_{0}, \mathbf{e}\right)$. We know that there is some point $p \in Y_{\mathbf{e}}$ so that $d_{X}\left(p, h_{k}\right) \leq R^{\prime}+R^{\prime \prime}$. If $p=g_{j}$ for some $j$ there is nothing left to show. If $p=i d$, then $d_{X}\left(g_{0}, h_{k}\right) \leq$ $d_{X}\left(g_{0}, i d\right)+d_{X}\left(i d, h_{k}\right) \leq R^{\prime}+R^{\prime \prime}+\left|g_{0}\right|_{X}$. Finally, if $p \in \tau_{j}$ for some $j \geq 0$, we note that $p$ has depth at most $R^{\prime}+R^{\prime \prime}$, so it is distance at most $R^{\prime}+R^{\prime \prime}+2$ from an endpoint of $\tau_{j}$, and hence at most $R^{\prime}+R^{\prime \prime}+C+2$ from either $g_{j-1}$ or $g_{j}$. In each case, we have shown that $h_{k}$ lies in the $\left(R^{\prime}+R^{\prime \prime}+\left|g_{0}\right|_{X}+C+2\right)$-neighborhood of the associated quasi-geodesic sequence for $\left(g_{0}, \mathbf{e}\right)$; we can then argue symmetrically to obtain the desired uniform bound on Hausdorff distance.

## 5. Uniform nesting

In this section, we prove an analog of MMW22, Lemma 3.8] (there called the Uniform Contraction Lemma). More care is needed here because of the presence of parabolic elements.

We have seen that any two generalized codings of the same conical point have infinitely many nearby pairs of points along their quasi-geodesic sequences $g_{k}$ and $h_{k}$. The next condition says, roughly, that there are two possibilities: either these pairs of points are eventually uniformly spaced along the quasi-geodesic, or there is an infinite sequence of large parabolic jumps between them. In either case, one can control the behavior of a sequence of nested sets determined by one coding in terms of the other coding, which is what we will need to prove that codings determine a well-defined semiconjugacy between the standard action and a small perturbation.

Definition 5.1. Let $\left(g_{0}, \mathbf{e}\right)$ and $\left(h_{0}, \mathbf{f}\right)$ be generalized codings of the same conical point in $\partial(\Gamma, \mathcal{P})$. Let $g_{k}, h_{k}$ be their associated quasi-geodesic sequences, and let $W^{\mathbf{e}}(k)=W\left(\tau\left(e_{k}\right)\right)$ and $W^{\mathbf{f}}(k)=W\left(\tau\left(f_{k}\right)\right)$. This pair of codings has the $c$-uniform nesting property if for any $\varepsilon^{\prime}<c$, there are constants $D_{1}>0$ and $D_{2}=D_{2}\left(\varepsilon^{\prime}\right)>0$ so that at least one of the following conditions holds.
(1) (Uniform nesting with short words) There exist $N, M \in \mathbb{N}$ such that for every term in the sequence of indices $n_{k}:=k+M$, we have $\left|\mathbf{L a b}\left(e_{n_{k}}\right)\right|_{X} \leq$ $D_{2}$, there exists $m_{k}$ such that $d_{X}\left(g_{n_{k}}, h_{m_{k}}\right) \leq D_{1}$ and

$$
g_{n_{k}+N} \overline{W^{\mathbf{e}}\left(n_{k}+N\right)} \subset h_{m_{k}} W^{\mathbf{f}}\left(m_{k}\right)
$$

(2) (Uniform nesting with long parabolics) There are infinite sequences of indices $n_{k}, m_{k}$ such that for every $k \in \mathbb{N}, d_{X}\left(g_{n_{k}}, h_{m_{k}}\right) \leq D_{1}$ and

- $\tau\left(e_{n_{k}}\right)$ is a parabolic point;
- $g_{n_{k}} \bar{B}_{3 \varepsilon^{\prime}}\left(\tau\left(e_{n_{k}}\right)\right) \subset h_{m_{k}} W^{\mathbf{f}}\left(m_{k}\right)$;
- $\mathbf{L a b}\left(e_{n_{k}+1}\right) N_{\varepsilon}\left(W^{\mathbf{e}}\left(n_{k}+1\right)\right) \subset B_{\varepsilon^{\prime}}\left(\tau\left(e_{n_{k}}\right)\right)$, where $\varepsilon$ is as in Definition 3.3

Our main goal in this section is to prove:
Proposition 5.2. Given $g_{0}, h_{0} \in G$, there exists $c>0$ such that if $\left(g_{0}, \mathbf{e}\right)$ and $\left(h_{0}, \mathbf{f}\right)$ are generalized codings of the same conical point $\zeta \in \partial(\Gamma, \mathcal{P})$, then $\left(g_{0}, \mathbf{e}\right)$ and $\left(h_{0}, \mathbf{f}\right)$ have the $c$-uniform nesting property. Furthermore, the constant $D_{1}$ depends only on $g_{0}, h_{0}$, and the constants $N$ and $D_{2}$ depend only on $g_{0}, h_{0}$ and the choice of $\varepsilon^{\prime}<c$, and not on $\zeta$, $\mathbf{e}$, or $\mathbf{f}$.

As a first step towards the proof, the following lemma describes the behavior of codings that involve edges labeled by long words in $\Gamma$. Since codings are close to geodesics, these long words correspond to parabolics - geometrically, the geodesic has a long segment through the horosphere based at this parabolic point. The lemma makes precise the notion that two codings of the same point, being close to the same geodesic, have long segments in common horospheres.

Lemma 5.3 (Large jumps come from common parabolics). Given $g_{0}, h_{0} \in \Gamma$, there are constants $D_{1}, J>0$ so the following holds. Let $\left(g_{0}, \mathbf{e}\right)$ and $\left(h_{0}, \mathbf{f}\right)$ be two generalized codings of the same conical point $\zeta$, let $\mathbf{L a b}\left(e_{k}\right)=\alpha_{k}, \mathbf{L a b}\left(f_{k}\right)=\beta_{k}$, and let $\left(g_{k}\right)_{k \in \mathbb{N} \cup\{0\}},\left(h_{k}\right)_{k \in \mathbb{N} \cup\{0\}}$ be the respective associated quasi-geodesic sequences. Then for each $n$ with $\left|\alpha_{n}\right|_{X}>J$ there exists $m=m(n)$ such that
(1) $d_{X}\left(g_{n-1}, h_{m-1}\right)<D_{1}$ and $d_{X}\left(g_{n}, h_{m}\right)<D_{1}$;
(2) There exists $p \in \Pi$ and $g, h \in G$ such that $\iota\left(e_{n}\right)=g p$ and $\iota\left(f_{m}\right)=h p$;
(3) $g_{n-1} g, h_{m-1} h, g_{n}$ and $h_{m}$ are all in the same coset of $\Gamma_{p}$.

The rough idea of the proof is as follows. We consider a regular geodesic ray $\sigma$ in $X$ from $i d$ to $\zeta$, close to the quasi-geodesic sequences associated to both generalized codings. We first prove that, if the distance in $X$ between two consecutive points $g_{n-1}, g_{n}$ is large, then a geodesic segment between $g_{n-1}$ and $g_{n}$ must spend a large amount of its lifetime in some horoball $\mathcal{H}$ (this will follow from Lemma 5.4 below). Using the fact that the quasi-geodesic sequence tracks $\sigma$, we prove that $\sigma$ must also spend some large amount of time in the same horoball $\mathcal{H}$. If this time is long enough, we can even conclude that $\sigma$ spends some large time in a horoball $\mathcal{H}^{\prime}$ nested deeply inside of $\mathcal{H}$.

Then, using the fact that the quasi-geodesic sequence associated to $\mathbf{f}$ also tracks $\sigma$, we can show that there are points $h_{m-1}, h_{m}$ in this sequence on "either side" of $\mathcal{H}^{\prime}$. Since these points are far apart, a regular geodesic joining $h_{m-1}$ to $h_{m}$ must spend a long amount of time in $\mathcal{H}$, which essentially proves the lemma.

To make the above reasoning precise, we first prove two general lemmas about the geometry of the cusped space $X$. The first lemma gives us a way to estimate
the length of time a geodesic in $X$ spends inside a horoball $\mathcal{H}$ when one of the endpoints of the geodesic lies on the boundary of $\mathcal{H}$.
Lemma 5.4. Suppose that $\alpha \in G$ lies in a coset $g \Gamma_{p}$ for some $g \in \Gamma$ and $p \in \Pi$, and let $\mathcal{H} \subset X$ be the horoball in $X$ based at $g \Gamma_{p}$. Let $\tau$ be a regular geodesic in $X$ from id to $\alpha$. Then $\tau \cap \mathcal{H}$ contains a sub-segment with length at least $|\alpha|_{X}-\left(|g|_{X}+12 \delta\right)$.

Moreover, if $\mathcal{H}^{\prime} \neq \mathcal{H}$ is any other horoball in $X$, then any component of $\tau \cap \mathcal{H}^{\prime}$ has length at most $|g|_{X}+12 \delta$.

Proof. Note that the elements $g$ and $\alpha$ both lie on the boundary of the horoball $\mathcal{H}$. Let $\mathcal{H}$ be the $3 \delta$-horoball nested inside $\mathcal{H}$. (See Section 2 for definitions.) Let $a$ be the point on $\partial \mathcal{H}$ which is connected by a vertical path to $g$, and let $b$ be the point on $\partial \mathscr{H}$ which is connected by a vertical path to $\alpha$.

Consider a geodesic pentagon whose vertices are (in cyclic order) $i d, g, a, b$, and $\alpha$, so that the side connecting $i d$ to $\alpha$ is $\tau$. The sides $[g, a]$ and $[\alpha, b]$ are vertical, and we may suppose that the side $[a, b]$ is regular.

Every point on $\tau$ is within $3 \delta$ of some point on one of the other sides of this pentagon. At most the initial subsegment of length $|g|_{X}+6 \delta$ and the final subsegment of length $6 \delta$ can be close to some other side than $[a, b]$.

We deduce that a subsegment $\tau^{\prime}$ of length at least $|\alpha|_{X}-\left(|g|_{X}+12 \delta\right)$ is within $3 \delta$ of $[a, b]$, and hence within $3 \delta$ of $\check{\mathcal{H}}$. In particular $\tau^{\prime}$ is completely contained in $\mathcal{H}$, establishing the first part of the lemma.

The last sentence follows since horoballs have disjoint interior.
The next lemma is essentially a consequence of the quasi-convexity of horoballs in $X$.

Lemma 5.5 (Nearby geodesics enter common horoballs). Let $\mathcal{H} \subset X$ be a $k$ horoball for some $k \geq 0$, and let $\tau_{1}, \tau_{2}$ be two regular geodesic segments in $X$ such that the endpoints of $\tau_{1}$ lie within distance $L$ of the endpoints of $\tau_{2}$. If $\tau_{1} \cap \mathcal{H}$ contains a segment with length at least $T \geq 4 L+12 \delta+3$, then $\tau_{2} \cap \mathcal{H}$ contains a segment with length at least $T-(4 L+8 \delta)$.
Proof. Let $a_{1}, b_{1}$ and $a_{2}, b_{2}$ be the endpoints of $\tau_{1}, \tau_{2}$ respectively, so that $d_{X}\left(a_{1}, a_{2}\right) \leq$ $L$ and $d_{X}\left(b_{1}, b_{2}\right) \leq L$. We let $\check{\mathcal{H}}$ be the $(k+2 \delta)$-horoball nested inside of the $k$ horoball $\mathcal{H}$. Then, since $\tau_{1}$ is regular, and its intersection with $\mathcal{H}$ has length at least $T>4 \delta+3$, it also intersects $\mathscr{\mathcal { H }}$, and in fact the intersection contains a segment with length at least $T-4 \delta$. We let $x_{1}, y_{1}$ be the endpoints of such a segment, so that $a_{1}, x_{1}, y_{1}, b_{1}$ are arranged on $\tau_{1}$ in that order.

The length of $\tau_{1}$ is

$$
\begin{aligned}
d_{X}\left(a_{1}, x_{1}\right)+d_{X}\left(x_{1}, y_{1}\right)+d_{X}\left(y_{1}, b_{1}\right) & =d_{X}\left(a_{1}, x_{1}\right)+(T-4 \delta)+d_{X}\left(y_{1}, b_{1}\right) \\
& \geq d_{X}\left(a_{1}, x_{1}\right)+d_{X}\left(y_{1}, b_{1}\right)+4 L+8 \delta+3
\end{aligned}
$$

The geodesic $\tau_{2}$ has endpoints at most $L$ from those of $\tau_{1}$, so its length is at least $d_{X}\left(a_{1}, x_{1}\right)+d_{X}\left(y_{1}, b_{1}\right)+2 L+8 \delta+3$. In particular, there are points $x_{2}$ and $y_{2}$ of $\tau_{2}$ satisfying

$$
\begin{gathered}
d_{X}\left(a_{2}, x_{2}\right)=d_{X}\left(a_{1}, x_{1}\right)+L+2 \delta, \\
d_{X}\left(y_{2}, b_{2}\right)=d_{X}\left(y_{1}, b_{1}\right)+L+2 \delta .
\end{gathered}
$$

Moreover, the points $a_{2}, x_{2}, y_{2}, b_{2}$ must lie on the segment $\tau_{2}$ in that order, since

1) J: I rewrote this argument a bit. It looks like we can get away with $T \geq$ $4 L+8 \delta+3$. TODO Jason fix this carefully.

Consider a geodesic quadrilateral with opposite sides $\tau_{1}, \tau_{2}$. The sub-segment $\left[x_{2}, y_{2}\right] \subset \tau_{2}$ is contained in a $2 \delta$-neighborhood of the other three sides of this quadrilateral. In fact, $\left[x_{2}, y_{2}\right]$ must be contained in the $2 \delta$-neighborhood of $\left[x_{1}, y_{1}\right]$, meaning it is contained in the $2 \delta$-neighborhood of $\check{\mathcal{H}}$ and therefore in $\mathcal{H}$. Thus, this segment in $\tau_{2} \cap \mathcal{H}$ has length at least

$$
\left|\tau_{2}\right|-2 L-4 \delta-d_{X}\left(a_{1}, x_{1}\right)-d_{X}\left(y_{1}, b_{1}\right)
$$

Then, since $\left|\tau_{2}\right| \geq\left|\tau_{1}\right|-2 L$, by our choice of $x_{1}, y_{1}$ we have

$$
\left|\tau_{1}\right| \geq d_{X}\left(a_{1}, x_{1}\right)+(T-4 \delta)+d_{X}\left(y_{1}, b_{1}\right)
$$

so we obtain the desired bound.
Proof of Lemma 5.3. Let $C$ be the constant from Definition 4.14, which we recall is (partly) determined by fixing a group element $t_{q} \in \Gamma$ for each parabolic vertex $q \in Z$, satisfying $t_{q}^{-1} q \in \Pi$. Letting $R$ be the constant from Lemma 4.7, we set

$$
R^{\prime}=R+\max \left\{\left|g_{0}\right|_{X},\left|h_{0}\right|_{X}\right\}+2 \delta
$$

and then let

$$
J>11 R^{\prime}+2 C+50 \delta
$$

Consider two conical codings $\left(g_{0}, \mathbf{e}\right)$ and $\left(h_{0}, \mathbf{f}\right)$ of a point $\zeta \in \partial(\Gamma, \mathcal{P})$, and let $\left(g_{n}\right)_{n \in \mathbb{N} \cup\{0\}}$ and $\left(h_{m}\right)_{m \in \mathbb{N} \cup\{0\}}$ be the associated quasi-geodesic sequences. Fix some $n \in \mathbb{N}$ such that $\left|\alpha_{n}\right|_{X}>J$ labeled by $\alpha_{n}$ has its initial vertex at a parabolic point, meaning that $\alpha_{n}$ is in some coset $t_{q} \Gamma_{p}$ with $q=\iota\left(e_{n}\right)=t_{q} p$ and $p \in \Pi$. In particular $\alpha_{n}=t_{q} a$ where $a \in \Gamma_{p}$. Let $\mathcal{H}$ be the horoball associated to the coset $g_{n} \Gamma_{p}=g_{n-1} t_{q} \Gamma_{p}$, and let $\tau$ be a regular geodesic from $g_{n-1}$ to $g_{n}$. Now, $g_{n-1}^{-1} \tau$ is a regular geodesic from $i d$ to $\alpha_{n}=g_{n-1}^{-1} g_{n}$, so by Lemma 5.4. it contains a segment in $g_{n-1}^{-1} \mathcal{H}$ of length at least $J-(C+12 \delta)$. Thus, $\tau \cap \mathcal{H}$ contains a segment of length at least $J-(C+12 \delta)$.

Let $\sigma$ be a regular geodesic from $i d$ to $\zeta$. For a pair of points $a, b \in \sigma$, let $[a, b]$ denote the sub-segment of $\sigma$ with endpoints $a, b$. By Corollary 4.8, we can find a sequence $\left(x_{n}\right)_{n \in \mathbb{N}}$ on $\sigma$, so that $d_{X}\left(g_{n}, x_{n}\right) \leq R^{\prime}$. Then Lemma 5.5 implies that the intersection $\left[x_{n-1}, x_{n}\right] \cap \mathcal{H}$ contains a segment with length at least $J-C-4 R^{\prime}-20 \delta$.

We now wish to find consecutive $h_{m-1}, h_{m}$ in the quasi-geodesic sequence associated to $\left(h_{0}, \mathbf{f}\right)$ so that a regular geodesic between $h_{m-1}$ and $h_{m}$ spends all but a uniformly bounded amount of its length inside the horoball $\mathcal{H}$. For this, we let $\mathcal{H}^{\prime}$ be the $R^{\prime}$-horoball nested inside of $\mathcal{H}$. Since $R^{\prime}>2 \delta$ by definition, Lemma 2.1 implies that $\mathcal{H}^{\prime}$ is convex, so the intersection $\sigma \cap \mathcal{H}^{\prime}$ is a geodesic segment, which must have length at least $J-C-6 R^{\prime}-24 \delta>0$. Let $\sigma_{1}$ be the connected component of $\sigma \backslash \mathcal{H}^{\prime}$ containing $i d$ and let $\sigma_{2}$ be the unbounded connected component.

Since every element in our sequence $h_{m}$ lies in $\Gamma$, no $h_{m}$ can lie in an $R^{\prime}$ neighborhood of the $R^{\prime}$-horoball $\mathcal{H}^{\prime}$, and thus each $h_{m}$ lies within distance $R^{\prime}$ of exactly one of $\sigma_{1}$ or $\sigma_{2}$. We let $m$ be the first index so that $h_{m}$ is within distance $R^{\prime}$ of $\sigma_{2}$, so $h_{m-1}$ lies distance at most $R^{\prime}$ from $\sigma_{1}$. Let $y_{m-1}, y_{m}$ be points on $\sigma$ which are within distance $R^{\prime}$ of $h_{m-1}$ and $h_{m}$ respectively. These points must lie on either side of the intersection $\mathcal{H}^{\prime} \cap \sigma$, so the segment $\left[y_{m-1}, y_{m}\right] \cap \mathcal{H}^{\prime}$ is a geodesic segment with length at least $J-C-6 R^{\prime}-24 \delta$. Then, if $\tau^{\prime}$ is a regular geodesic between $h_{m-1}$ and $h_{m}$, Lemma 5.5 tells us that $\tau^{\prime} \cap \mathcal{H}^{\prime}$ contains a segment of length at least $J-C-10 R^{\prime}-32 \delta>C+12 \delta$, and therefore so does the intersection $\tau^{\prime} \cap \mathcal{H}$.

In particular, we have $d_{X}\left(h_{m-1}, h_{m}\right)=\left|\beta_{m}\right|_{X}=\left|\tau^{\prime}\right|>C$, so the initial vertex of the edge labeled by $\beta_{m}$ is a parabolic point $q^{\prime}=t_{q^{\prime}} p^{\prime} \in Z$ for some $p^{\prime} \in \Pi$. Lemma 5.4 implies that the horoball based on $t_{q^{\prime}} p^{\prime}$ is the only horoball which $\tau^{\prime}$ can intersect in a segment of length longer than $C+12 \delta$. Since $\tau^{\prime}$ meets $\mathcal{H}$ in a segment longer than this, we must have $q=q^{\prime}$ and $p^{\prime}=p$, establishing the last two items of the lemma.

It remains to bound $d_{X}\left(g_{n-1}, h_{m-1}\right)$ and $d_{X}\left(g_{n}, h_{m}\right)$. We first show that $\tau$ and $\tau^{\prime}$ cross $\mathcal{H}$ in the same direction. That is, we show:

Claim 1. $g_{n-1}$ is in the $R^{\prime}$-neighborhood of the initial segment $\sigma_{1}$ of $\sigma$, and $g_{n}$ is in the $R^{\prime}$-neighborhood of the final ray $\sigma_{2}$.

Proof. The claim essentially follows from the fact that the the distance $d_{X}\left(g_{n-1}, g_{n}\right)$ is large and from the bounded backtracking property of the quasi-geodesic sequence $\left(g_{n}\right)_{n \in \mathbb{N}}$ (Corollary 4.12). To be specific, we consider the points $x_{n-1}, x_{n}$ on $\sigma$ which are within distance $R^{\prime}$ of $g_{n-1}, g_{n}$ respectively. Recall that the regular geodesic $\tau$ between $g_{n-1}$ and $g_{n}$ intersects $\mathcal{H}$ in a segment of length at least $J-C-12 \delta$, so $\tau \cap \mathcal{H}^{\prime}$ contains a segment of length at least $J-C-2 R^{\prime}-12 \delta$. Then Lemma 5.5 implies that $\left[x_{n-1}, x_{n}\right] \cap \mathcal{H}^{\prime}$ contains a segment of length at least $J-C-6 R^{\prime}-20 \delta>0$. So, either $x_{n-1} \in \sigma_{1}$ and $x_{n} \in \sigma_{2}$, or vice versa.

However, if $x_{n-1} \in \sigma_{2}$ and $x_{n} \in \sigma_{1}$, then

$$
d_{X}\left(i d, x_{n-1}\right)=d_{X}\left(i d, x_{n}\right)+d_{X}\left(x_{n-1}, x_{n}\right)
$$

implying that

$$
d_{X}\left(i d, x_{n}\right) \leq d_{X}\left(i d, x_{n-1}\right)-\left(J-C-6 R^{\prime}-24 \delta\right)
$$

Since $d_{X}\left(x_{n-1}, g_{n-1}\right) \leq R^{\prime}$ and $d_{X}\left(x_{n}, g_{n}\right) \leq R^{\prime}$, this would imply $\left|g_{n}\right|_{X} \leq\left|g_{n-1}\right|_{X}-$ $\left(J-C-8 R^{\prime}-24 \delta\right)<\left|g_{n-1}\right|_{X}-\left(3 R^{\prime}+2 \delta\right)$. Since $R^{\prime} \geq R+\left|g_{0}\right|_{X}+2 \delta$ by definition, this contradicts Corollary 4.12. This proves the claim.

We now consider the points $x_{n-1}, y_{m-1}$ on $\sigma_{1}$ within distance $R^{\prime}$ of $g_{n-1}, h_{m-1}$. Let $z_{1}, z_{2}$ be the endpoints of $\sigma_{1}$ and $\sigma_{2}$ on $\partial \mathcal{H}^{\prime}$, respectively.

Since $d_{X}\left(g_{n-1}, \mathcal{H}^{\prime}\right) \leq C+R^{\prime}$ and $d_{X}\left(h_{m-1}, \mathcal{H}^{\prime}\right) \leq C+R^{\prime}$, we have $d_{X}\left(x_{n-1}, \mathcal{H}^{\prime}\right) \leq$ $2 R^{\prime}+C$ and $d_{X}\left(y_{m-1}, \mathcal{H}^{\prime}\right) \leq 2 R^{\prime}+C$. Then, we apply Lemma 2.2 to the subsegment $\left[x_{n-1}, z_{2}\right]$ and the $R^{\prime}$-horoball $\mathcal{H}^{\prime}$ to deduce that $d_{X}\left(x_{n-1}, \partial \mathcal{H}^{\prime}\right)$ differs by at most $\delta$ from $d_{X}\left(x_{n-1}, z_{1}\right)$, and similarly for $y_{m-1}$. In particular, $d_{X}\left(x_{n-1}, y_{m-1}\right) \leq$ $2\left(2 R^{\prime}+C+\delta\right)$, hence $d_{X}\left(g_{n-1}, h_{m-1}\right) \leq 6 R^{\prime}+2 C+4 \delta$.

A nearly identical argument applied to the points $x_{n}, y_{m}$ (with the roles of $\sigma_{1}, z_{1}$ interchanged with the roles of $\left.\sigma_{2}, z_{2}\right)$ shows that $d_{X}\left(g_{n}, h_{m}\right)$ is also at most $6 R^{\prime}+$ $2 C+4 \delta$, meaning we can set $D_{1}=6 R^{\prime}+2 C+4 \delta$.

Proof of Proposition 5.2. Let $\left(g_{0}, \mathbf{e}\right)$ and $\left(h_{0}, \mathbf{f}\right)$ be generalized codings of the same conical point $\zeta$, with $\mathbf{L a b}\left(e_{n}\right)=\alpha_{n}, \mathbf{L a b}\left(f_{m}\right)=\beta_{m}$ and let $\left(g_{n}\right)_{n \in \mathbb{N} \cup\{0\}}$ and $\left(h_{m}\right)_{m \in \mathbb{N} \cup\{0\}}$ be the associated quasigeodesic sequences.

First, we set the constants $c$ and $D_{1}$. (The numbers $D_{2}, N$ depends on $\varepsilon^{\prime}$ so they will be set later.) Choose $D_{1}$ and $J$ so that they are at least as large as the corresponding constants in Lemma 5.3 , and so that $D_{1}$ is also at least the Hausdorff distance bound in Lemma 4.13. Note that these only depend on $g_{0}$ and $h_{0}$, not $\mathbf{e}, \mathbf{f}$ or $\zeta$.

By Lemma 5.3, whenever $\left|\alpha_{n}\right|_{X}>J$, there exists a parabolic point $p \in \Pi$, an index $m$, and elements $g, h \in \Gamma$ such that $d\left(g_{n-1}, h_{m-1}\right)<D_{1}, \iota\left(e_{n}\right)=g p$ and $\iota\left(f_{m}\right)=h p$, and the elements $g_{n-1} g$ and $h_{m-1} h$ lie in the same coset of $\Gamma_{p}$.

Thus, $g \Gamma_{p}=\left(g_{n-1}^{-1} h_{m-1}\right) h \Gamma_{p}$, and $\left|g_{n-1}^{-1} h_{m-1}\right|_{X}<D_{1}$, so $g_{n-1}^{-1} h_{m-1}$ lies in a finite set $F_{1}:=\left\{f \in \Gamma:|f|_{X}<D_{1}\right\}$. Restating the above, we have $g p=f h p$, for $f \in F_{1}$. Since $h p \in W(h p)$, we have $f h p=g p \in f W(h p)$. Consider all possible triples $(z, y, f)$ such that $z, y \in Z, f \in F_{1}$, and $z \in f W(y)$. There are finitely many such, so we may choose some $c>0$ such that $\bar{B}_{3 c}(z) \subset f W(y)$ holds for every such triple.

Now fix any $\varepsilon^{\prime}<c$, and choose $D_{2}^{\prime}=D_{2}^{\prime}\left(\varepsilon^{\prime}\right)>J$ large enough so that, for each edge from $z$ to a vertex $x$ where $z=g p$ is parabolic, and each $\alpha \in L(z)$, if $|\alpha|_{X}>D_{2}^{\prime}$ then $\alpha \bar{N}_{\varepsilon}(W(x)) \subset B_{\varepsilon^{\prime}}(z)$. We know such a $D_{2}^{\prime}$ exists because only finitely many elements of the coset $g \Gamma_{p}$ fail this contraction condition: as we observed at the beginning of Remark 3.10. since the edge inclusion condition

$$
\alpha \bar{N}_{\varepsilon}(W(x)) \subset \alpha \hat{W}(z) \subset W(z)
$$

holds for all but finitely many $\alpha \in g \Gamma_{p}$, the closed neighborhood $\bar{N}_{\varepsilon}(W(x))$ cannot contain $p$ and therefore all but finitely many $\alpha \in g \Gamma_{p}$ take $\bar{N}_{\varepsilon}(W(x))$ into an arbitrarily small neighborhood of $z$. We define $D_{2}=D_{2}\left(\varepsilon^{\prime}\right):=D_{2}^{\prime}\left(\varepsilon^{\prime}\right)+2 D_{1}$. Again, this depends on $h_{0}, g_{0}$ and $\varepsilon^{\prime}$, but not the strict codings $\mathbf{e}, \mathbf{f}$ or the point $\zeta$.

We now can prove that the generalized codings satisfy uniform nesting. As a first case, suppose $\left|\alpha_{n}\right|_{X}>D_{2}^{\prime}$ for infinitely many $n$. We will show that, in this case, we have uniform nesting with long parabolics. Choose an infinite sequence of indices $n_{k}$ so that $\left|\alpha_{n_{k}+1}\right|_{X}>D_{2}^{\prime}$ is always satisfied. Lemma 5.3 then provides a sequence of indices $m_{k}$ with $d_{X}\left(g_{n_{k}}, h_{m_{k}}\right)<D_{1}$ and $d_{X}\left(g_{n_{k}+1}, h_{m_{k}+1}\right)<D_{1}$, which satisfies all of the requirements of "uniform nesting with long parabolics" by our choice of constants $D_{2}^{\prime}, \varepsilon^{\prime}$. This finishes the proof in this case.

On the other hand, if $\left|\beta_{m}\right|_{X}>D_{2}=D_{2}^{\prime}+2 D_{1}$ is satisfied for infinitely many $m$, then we can use Lemma 5.3 again to find an an infinite subsequence $\left(\alpha_{n_{k}}\right)_{k \in \mathbb{N}}$ so that $\left|\alpha_{n_{k}}\right|_{X}>D_{2}^{\prime}$ for every $k$, and we are in the previous case.

If neither of the first two cases hold, then we know that both $\left|\alpha_{n}\right|_{X}$ and $\left|\beta_{m}\right|_{X}$ are bounded by $D_{2}$ for all but finitely many $n, m$, respectively. For this case, we will create new generalized codings of $\zeta$ by "shifting the indices:" we replace $g_{0}$ and $h_{0}$ with terms further along in the associated quasi-geodesic sequences, and truncating the first terms of the sequence so that all labels are bounded by $D_{2}$. This will put us in a position to consider a sub-automaton only including edges with short labels, and then apply Lemma A. 3 from the Appendix to conclude the proof.

In more detail: first, choose $M$ large enough so that $\left|\alpha_{n}\right|_{X} \leq D_{2}$ for all $n \geq$ M. Lemma 4.13 tells us that for each $n \in \mathbb{N}$, there is some index $m(n)$ so that $d_{X}\left(g_{n}, h_{m(n)}\right)<D_{1}$. Lemma 4.10 implies that $m(n)$ tends to infinity as $n$ tends to infinity, so increasing $M$ if necessary, we can ensure that $\left|\beta_{k}\right|_{X} \leq D_{2}$ for every $k \geq m(M)$.

Let $\mathbf{e}^{\prime}$ be the sub-path of $\mathbf{e}$ starting with the edge $e_{M}$ and let $\mathbf{f}^{\prime}$ be sub-path of $\mathbf{f}$ starting with the edge $f_{m(M)}$. Consider the generalized codings $\left(g_{M-1}, \mathbf{e}^{\prime}\right)$ and $\left(h_{m(M)-1}, \mathbf{f}^{\prime}\right)$, and let $g_{n}^{\prime}=g_{n+M-1}$ and $h_{m}^{\prime}=h_{m+m(M)-1}$ be their associated quasi-geodesic sequences. By construction, both of these codings are generalized codings of $\zeta$, and their associated quasi-geodesic sequences are tails of the associated
quasi-geodesic sequences for $\left(g_{0}, \mathbf{e}\right)$ and $\left(h_{0}, \mathbf{f}\right)$, respectively. Further, the label sequences of $\mathbf{e}^{\prime}$ and $\mathbf{f}^{\prime}$ consist of elements whose length in $X$ is bounded by $D_{2}$.

Let $\mathcal{F}$ be the subgraph of $\mathcal{G}$ obtained by deleting all labels of length more than $D_{2}$, and then deleting all edges with empty label set. Then $\mathcal{F}$ is a finitary point coder in the sense defined in Appendix A, and $\left(g_{M-1}, \mathbf{e}^{\prime}\right)$ and $\left(h_{m(M)-1}, \mathbf{f}^{\prime}\right)$ are generalized $\mathcal{F}$-codings.

Let $F$ be the finite subset of $\Gamma$ consisting of elements of length at most $D_{1}$, and apply this to Lemma A.3. We conclude there is a constant $N>0$, so that whenever $d_{X}\left(g_{n}^{\prime}, h_{m}^{\prime}\right)<D_{1}$, we have $g_{n+N}^{\prime} \overline{W\left(z_{n+N}\right)} \subset h_{m}^{\prime} W\left(y_{m}\right)$, where $z_{k}=\tau\left(e_{k}^{\prime}\right)$ and $y_{k}=\tau\left(f_{k}^{\prime}\right)$. Translating this statement, for each $m_{k}$ such that $d_{X}\left(g_{n_{k}}, h_{m_{k}}\right) \leq D_{1}$ and $n_{k}>M$, we have

$$
g_{n_{k}+N}^{\prime} \overline{W^{\mathbf{e}}\left(n_{k}+N\right)} \subset h_{m_{k}} W^{\mathbf{f}}\left(m_{k}\right)
$$

The constant $N$ in the above depends only on the point coder $\mathcal{F}$, which in turn depends only on $D_{2}$ and the original automaton $\mathcal{G}$, so this completes the proof.

Remark 5.6. The containment

$$
g_{n_{k}+N} \overline{W^{\mathbf{e}}\left(n_{k}+N\right)} \subset h_{m_{k}} W^{\mathbf{f}}\left(m_{k}\right)
$$

from uniform nesting with short words is equivalent to

$$
g_{n_{k}} \alpha_{n_{k}+1} \ldots \alpha_{n_{k}+N} \overline{W^{\mathbf{e}}\left(n_{k}+N\right)} \subset h_{m_{k}} W^{\mathbf{f}}\left(m_{k}\right)
$$

or, multiplying on the left by $g_{n_{k}}^{-1}$,

$$
\alpha_{n_{k}+1} \ldots \alpha_{n_{k}+N} \overline{W^{\mathbf{e}}\left(n_{k}+N\right)} \subset g_{n_{k}}^{-1} h_{m_{k}} W^{\mathbf{f}}\left(m_{k}\right)
$$

Since the assumptions of uniform nesting with short words stipulate that $\left|\alpha_{n_{k}}\right| \leq$ $D_{2}$, and $\left|g_{n_{k}}^{-1} h_{m_{k}}\right|_{X}<R$, and since there are only finitely many sets of the form $W(z)$, the inclusions given by $\dagger$ are only finite in number. So these inclusions correspond to finitely many open conditions, meaning they are stable under small perturbation. This is essential to our argument in Lemma 6.13.

Similarly, the containments $g_{n_{k}} \bar{B}_{3 \varepsilon^{\prime}}\left(\iota\left(e_{n_{k}+1}\right)\right) \subset h_{m_{k}} W^{\mathbf{e}}\left(m_{k}+1\right)$ from the parabolic nesting conditions are only finite in number.

## 6. Proof of main theorem

Thus far we have suppressed notation for the action of $\Gamma$ on its boundary, simply writing $g(\zeta)$ or $g \zeta$ for the image of $\zeta$ under $g$. We will now need to consider other actions of $\Gamma$ on this space, so we reintroduce the following notation.

Notation 6.1. As in the introduction, let $\rho_{0}: \Gamma \rightarrow \operatorname{Homeo}(\partial(\Gamma, \mathcal{P}))$ denote the standard action of $\Gamma$ on its Bowditch boundary. Thus, what was previously written $g W\left(z_{k}\right)$ now becomes $\rho_{0}(g) W\left(z_{k}\right)$, for example.
Definition 6.2. Given $\mathcal{V} \subset C(\partial(\Gamma, \mathcal{P}))$, we define $\mathcal{R}_{\mathcal{V}} \subset \operatorname{Hom}(\Gamma, \operatorname{Homeo}(\partial(\Gamma, \mathcal{P})))$ to be the set of representations $\rho$ such that, for each parabolic point $p \in \mathcal{P}$ with stabilizer $P=\Gamma_{p}$, there exists $\phi_{p} \in \mathcal{V}$ such that $\left.\rho\right|_{P}$ is an extension of $\left.\rho_{0}\right|_{P}$ via $\phi_{p}$.
Remark 6.3. The map $\phi_{p}$ defining a semiconjugacy for the action of $P$ as in Definition 6.2 is a priori not determined by the representation $\rho \in \mathcal{R}_{\mathcal{V}}$. To get around this, for the rest of this section, whenever we fix $\rho \in \mathcal{R}_{\mathcal{V}}$ for some $\mathcal{V} \subset$ $C(\partial(\Gamma, \mathcal{P}))$, then for each $p \in \Pi$ we implicitly choose a semi-conjugacy $\phi_{p} \in \mathcal{V}$ which extends the restriction of $\rho_{0}$ to $P=\Gamma_{p}$.

Notation 6.4. Assuming that some action $\rho \in \mathcal{R}_{\mathcal{V}}$ has been fixed, then for each parabolic point $z=\rho_{0}(g) p$, where $p \in \Pi$, we let $\phi_{z}:=\rho_{0}(g) \phi_{p} \rho(g)^{-1}$.

Observe the definition of $\phi_{z}$ depends only on $z$ and $\phi_{p}$, and not on the choice of $g \in \Gamma$ such that $z=\rho_{0}(g) p$. To see this, suppose $\rho_{0}(g) p=\rho_{0}(h) p$. Then

$$
\rho_{0}(g) \phi_{p} \rho(g)^{-1}=\rho_{0}(h) \rho_{0}\left(h^{-1} g\right) \phi_{p} \rho\left(h^{-1} g\right)^{-1} \rho\left(h^{-1}\right) .
$$

Since $h^{-1} g \in \Gamma_{p}, \rho_{0}\left(h^{-1} g\right) \phi_{p}=\phi_{p} \rho\left(h^{-1} g\right)$, which shows

$$
\rho_{0}(g) \phi_{p} \rho(g)^{-1}=\rho_{0}(h) \phi_{p} \rho(h)^{-1}
$$

as desired.
In addition, note that for fixed $z$, if $\rho$ approaches $\rho_{0}$, and $\phi_{p}$ tends to the identity, then $\phi_{z}$ tends to the identity as well. We also record the following.

Lemma 6.5. If $z=\rho_{0}(g) p$, then for any $x \in \partial(\Gamma, \mathcal{P})$ and any $\alpha \in g \Gamma_{p}$, we have

$$
\begin{equation*}
\phi_{z}(\rho(\alpha) x)=\rho_{0}(\alpha) \phi_{p}(x) \tag{3}
\end{equation*}
$$

Proof. Let $x$ be given, and suppose that $z=\rho_{0}(g) p$ and $\alpha=g h$ for $h \in \Gamma_{p}$. Then

$$
\begin{aligned}
\phi_{z}(\rho(\alpha) x) & =\phi_{z}(\rho(g h) x) \\
& =\rho_{0}(g) \phi_{p}\left(\rho(g)^{-1} \rho(g h) x\right) \\
& =\rho_{0}(g) \phi_{p}(\rho(h) x) \\
& =\rho_{0}(g h) \phi_{p}(x)=\rho_{0}(\alpha) \phi_{p}(x) .
\end{aligned}
$$

### 6.1. Specifying the neighborhoods $\mathcal{U}$ and $\mathcal{V}^{\prime}$.

Definition 6.6. Given a subset $\mathcal{V} \subset C(\partial(\Gamma, \mathcal{P}))$ and a representation $\rho \in \mathcal{R} \mathcal{V}$, we define families of sets $\left\{V_{\rho}(z)\right\}_{z \in Z}$ and $\left\{\hat{V}_{\rho}(z)\right\}_{z \in Z}$ as follows.

- If $z$ is a conical limit point, then we define

$$
V_{\rho}(z)=V(z), \quad \hat{V}_{\rho}(z)=\rho\left(\alpha_{z}^{-1}\right) V_{\rho}(z)
$$

where $\alpha_{z}$ is the unique element in the label set $L(z)$.

- If $z=\rho_{0}(g) p$ for some $g \in \Gamma, p \in \Pi$, we define

$$
V_{\rho}(z)=\phi_{z}^{-1}(V(z))
$$

and define

$$
\hat{V}_{\rho}(z)=\phi_{p}^{-1}(\hat{V}(z))
$$

Definition 6.7. Suppose that $\mathcal{V} \subset C(\partial(\Gamma, \mathcal{P}))$ and $\rho \in \mathcal{R}_{\mathcal{V}}$. We say that $\rho$ has the same combinatorics as the standard action $\rho_{0}$ if the following conditions hold:
(i) The collection $\left\{V_{\rho}(z)\right\}_{z \in Z}$ is an open covering of $\partial(\Gamma, \mathcal{P})$.
(ii) For every $z \in Z$, we have $V_{\rho}(z) \subset W(z)$.
(iii) For any $y, z \in Z$, we have $\hat{V}_{\rho}(y) \cap V_{\rho}(z)=\emptyset$ iff $\hat{V}(y) \cap V(z)=\emptyset$.
(iv) If there is an edge from $z$ to $y$ in $\mathcal{G}$ labeled by $\alpha$, then $\rho(\alpha)(W(y)) \subset W(z)$.

Lemma 6.8 (Same combinatorics is relatively open). For any sufficiently small neighborhood $\mathcal{V}^{\prime}$ of the identity in $C(\partial(\Gamma, \mathcal{P}))$ and any sufficiently small neighborhood $\mathcal{U}$ of $\rho_{0}$ in $\operatorname{Homeo}(\Gamma, \partial(\Gamma, \mathcal{P}))$, each $\rho \in \mathcal{U} \cap \mathcal{R}_{\mathcal{V}^{\prime}}$ has the same combinatorics as $\rho_{0}$.

Proof. First, we ensure that Item (i) in the definition holds. Let $r$ be a Lebesgue number for the original open covering $\{V(z)\}_{z \in Z}$, so that every set of diameter at most $r$ is contained in some $V(z)$. We may choose $\mathcal{V}^{\prime}$ small enough so that $d_{\partial}\left(\phi_{z}(x), x\right)<r / 2$ for every parabolic point $z \in Z$ and $x \in \partial(\Gamma, \mathcal{P})$.

Then, for any $x \in \partial(\Gamma, \mathcal{P})$, the $(r / 2)$-ball about $x$ is contained in some $V(z)$, where $z \in \partial(\Gamma, \mathcal{P})$ is either conical or parabolic. If $z$ is conical then $V_{\rho}(z)=V(z)$ and thus $x \in V_{\rho}(z)$. Otherwise, if $z$ is parabolic, then $\phi_{z}(x)$ lies in $B_{r / 2}(x) \subset V(z)$, hence $x \in \phi_{z}^{-1}(V(z))=V_{\rho}(z)$.

Item (ii) can be arranged because $\overline{V(z)} \subset W(z)$ for each $z$ (see Condition (C5). In particular, there is some minimum distance from any $V(z)$ to $\partial(\Gamma, \mathcal{P})-W(z)$, and we can choose $\mathcal{V}^{\prime}$ small enough so that no $\phi_{z}$ moves any point more than that distance.

For Item (iii) we argue similarly. Property (C6) from Proposition 3.7 implies there is a minimum distance from any $V(z)$ to any disjoint $\hat{V}(y)$. Shrinking $\mathcal{V}^{\prime}$ if necessary, we may assume that no $\phi_{z}$ moves any point more than half that distance. By choosing sufficiently small $\mathcal{U}$, we can ensure that the distance between $\rho\left(\alpha_{z}\right)$ and $\rho_{0}\left(\alpha_{z}\right)$ is also at most half that distance. This will ensure that $V(z) \cap \hat{V}(y)=\emptyset$ implies $V_{\rho}(z) \cap \hat{V}_{\rho}(y)=\emptyset$. For the converse, observe that there is some positive radius $r$ so that each nonempty intersection $V(z) \cap \hat{V}(y)$ contains a ball of radius $r$. The sets $V_{\rho}(z)$ and $\hat{V}_{\rho}(y)$ each contain the preimage of this ball by a continuous map arbitrarily close to the identity, so if $\mathcal{V}^{\prime}$ and $\mathcal{U}$ are small enough then these preimages have nonempty intersection.

We now turn to condition (iv) By condition (E1) in Proposition 3.9 we have $\rho_{0}(\alpha) \bar{N}_{\varepsilon}(W(y)) \subsetneq W(z)$ for every edge from $z$ to $y$ labeled by $\alpha$. For conical vertices $z$, provided $\rho$ is a small enough perturbation of $\rho_{0}$, each of the containments $\rho(\alpha)(W(y)) \subset W(z)$ will hold, since there are only finitely many such edges and labels. For parabolic vertices, we argue as follows.

Consider the constants $\epsilon_{z}$ from Remark 3.10 and fix $\epsilon_{\min } \leq \min \left\{\epsilon_{z}: z \in\right.$ $Z$ parabolic\}. The inclusion (1) from Remark 3.10 says if $z$ is connected to $y$ by an edge labeled $\alpha$, we have

$$
\begin{equation*}
N_{\epsilon_{\min }}\left(\rho_{0}(\alpha)\left(N_{\varepsilon} W(y)\right)\right) \subset W(z) \tag{4}
\end{equation*}
$$

We choose our neighborhood $\mathcal{V}^{\prime}$ small enough so that, for each of the finitely many parabolic vertices $z \in Z$, the semi-conjugacy $\phi_{z}$ satisfies $d_{\partial}\left(x, \phi_{z}(x)\right)<$ $\min \left\{\epsilon_{\min }, \varepsilon\right\}$. This ensures that for any subset $A \subset \partial(\Gamma, \mathcal{P})$ we have $\phi_{z}(A) \subset N_{\varepsilon}(A)$ and $\phi_{z}^{-1}(A) \subset N_{\epsilon_{\min }}(A)$. In particular, we have $\phi_{z} W(y) \subset N_{\varepsilon}(W(y))$, so our choice of $\epsilon_{\min }$ and the containment from (4) above ensures that

$$
\rho(\alpha) W(y) \subset \phi_{z}^{-1} \phi_{z} \rho(\alpha) W(y) \subset N_{\epsilon_{\min }}\left(\rho_{0}\left(\alpha \phi_{z} W(y)\right) \subset W(z)\right.
$$

as desired.
Our next step is to define $(\mathcal{G}, \rho)$-codings, which provide a modified notion of a $\mathcal{G}$-coding which is compatible with the perturbed action $\rho$ instead of the standard action $\rho_{0}$. A $\left(\mathcal{G}, \rho_{0}\right)$-coding is the same thing as a $\mathcal{G}$-coding, but since our convention in this section is to make the standard action explicit, we will only refer to these as $\left(\mathcal{G}, \rho_{0}\right)$-codings from this point forward.
Definition 6.9. Let $\mathcal{V} \subset C(\partial(\Gamma, \mathcal{P}))$, and suppose that $\rho \in \mathcal{R}_{\mathcal{V}}$ has the same combinatorics as $\rho_{0}$. If $\mathbf{e}=\left(e_{k}\right)_{k \in \mathbb{N}}$ is an infinite edge path in $\mathcal{G}$ with $\mathbf{L a b}\left(e_{k}\right)=\alpha_{k}$,
we say $\mathbf{e}$ is a $(\mathcal{G}, \rho)$-coding for $\zeta$ if

$$
\zeta \in \bigcap_{k=1}^{\infty} \rho\left(\alpha_{1}\right) \cdots \rho\left(\alpha_{k}\right) W\left(z_{k}\right) .
$$

If $e_{1} \ldots e_{n}$ is a finite edge path giving a $\left(\mathcal{G}, \rho_{0}\right)$-coding for a parabolic point $z \in \partial(\Gamma, \mathcal{P})$, we say that it is a $(\mathcal{G}, \rho)$-coding for $\zeta$ if $\zeta \in \phi_{z}^{-1}(z)$, or equivalently if $\zeta \in \rho\left(\alpha_{1} \cdots \alpha_{n}\right) \phi_{z_{n}}^{-1}\left(z_{n}\right)$, where $z_{n}=\tau\left(e_{n}\right)$.
Lemma 6.10. Let $\mathcal{V} \subset C(\partial(\Gamma, \mathcal{P}))$, and suppose that $\rho \in \mathcal{R}_{\mathcal{V}}$ has the same combinatorics as $\rho_{0}$. Then every point in $\partial(\Gamma, \mathcal{P})$ has a $(\mathcal{G}, \rho)$-coding.

Proof. The proof follows the same strategy of Lemma 4.5. The first part of the inductive procedure goes through verbatim, replacing the sets $V(z)$ with $V_{\rho}(z)$, and elements $\alpha_{i}$ with $\rho\left(\alpha_{i}\right)$. The only modification required occurs at the inductive step when $z_{n}=\tau\left(e_{n}\right)$ is a parabolic rather than conical limit point. In this case we simply need to pay attention to the semi-conjugacies $\phi_{z_{n}}$.

In detail, adopting the notation and setting from the proof of Lemma 4.5 suppose we are given $\zeta \in \partial(\Gamma, \mathcal{P})$, and assume we have found a partial coding so that $\zeta \in \rho\left(\alpha_{1} \cdots \alpha_{n}\right) V_{\rho}\left(z_{n}\right)$ where $z_{n}$ is a parabolic point. If $\zeta \in \rho\left(\alpha_{1} \cdots \alpha_{n}\right) \phi_{z_{n}}^{-1}\left(z_{n}\right)$, then we have found a parabolic $(\mathcal{G}, \rho)$-coding for $\zeta$ and are done. Otherwise, $\zeta \notin$ $\rho\left(\alpha_{1} \cdots \alpha_{n}\right) \phi_{z_{n}}^{-1}\left(z_{n}\right)$. Let $\zeta_{n}:=\rho\left(\alpha_{1} \cdots \alpha_{n}\right)^{-1} \zeta$, so that $\zeta_{n} \in V_{\rho}\left(z_{n}\right)-\phi_{z_{n}}^{-1}\left(z_{n}\right)$. Then $\phi_{z_{n}}\left(\zeta_{n}\right) \in V\left(z_{n}\right)-\left\{z_{n}\right\}$ by the definition of $V_{\rho}\left(z_{n}\right)$. So, by property (C5) of the $\rho_{0}$-automaton, there is some $\alpha_{n+1} \in L\left(z_{n}\right)$ so that $\rho_{0}\left(\alpha_{n+1}^{-1}\right) \phi_{z_{n}}\left(\zeta_{n}\right) \in \hat{V}\left(z_{n}\right)$.

We can then apply Lemma 6.5 (with $x=\rho\left(\alpha_{n+1}^{-1}\right) \zeta_{n}$ ) to see that

$$
\rho_{0}\left(\alpha_{n+1}^{-1}\right) \phi_{z_{n}}\left(\zeta_{n}\right)=\phi_{p}\left(\rho\left(\alpha_{n+1}^{-1}\right) \zeta_{n}\right) .
$$

We conclude that $\phi_{p}\left(\rho\left(\alpha_{n+1}^{-1} \zeta_{n}\right)\right) \in \hat{V}\left(z_{n}\right)$. So, setting $\zeta_{n+1}:=\rho\left(\alpha_{n+1}^{-1}\right) \zeta_{n}$, we have

$$
\zeta_{n+1} \in \phi_{p}^{-1}\left(\hat{V}\left(z_{n}\right)\right)=\hat{V}_{\rho}\left(z_{n}\right)
$$

Since the $V_{\rho}(z)$ sets still cover $\partial(\Gamma, \mathcal{P})$, there is some $z_{n+1}$ with $\zeta_{n+1} \in V_{\rho}\left(z_{n+1}\right)$. Since $\rho$ has the same combinatorics as $\rho_{0}$, and $\zeta_{n}$ lies in $\hat{V}_{\rho}\left(z_{n}\right) \cap V_{\rho}\left(z_{n+1}\right)$ there is an edge in $\mathcal{G}$ from $z_{n}$ to $z_{n+1}$, which completes the inductive step.

Convention 6.11 (Choosing constants). For each pair $s, s^{\prime}$ in $\mathcal{S} \cup\{i d\}$, Proposition 5.2 gives a constant $c\left(s, s^{\prime}\right)$ such that any generalized codings of a common point of the form $(s, \mathbf{e})$ and $\left(s^{\prime}, \mathbf{f}\right)$ satisfy $c$-uniform nesting. Fix $\varepsilon^{\prime}<\min \left\{c\left(s, s^{\prime}\right): s, s^{\prime} \in\right.$ $\mathcal{S} \cup\{i d\}\}$.

Proposition 5.2 now states that, for each pair $\left(s, s^{\prime}\right)$, for this fixed $\varepsilon^{\prime}$ there exist constants $N\left(s, s^{\prime}\right), D_{1}\left(s, s^{\prime}\right)$ and $D_{2}\left(s, s^{\prime}\right)$ so that, for every pair of generalized codings $(s, \mathbf{e})$ and $\left(s^{\prime}, \mathbf{f}\right)$ of a common conical point, uniform nesting is satisfied with the constants $N\left(s, s^{\prime}\right), D_{1}\left(s, s^{\prime}\right)$ and $D_{2}\left(s, s^{\prime}\right)$ and $\varepsilon^{\prime}$. Fix $N, D_{1}$ and $D_{2}$ greater than the maximum of all such respective constants ranging over all pairs $s, s^{\prime} \in \mathcal{S} \cup\{i d\}$.

We note that these constants also implicitly depended on $\varepsilon$, which was specified in Definition 3.3 using our target neighborhood $\mathcal{V}$, and will reappear in Lemma 6.19

Lemma 6.12. There exists an open neighborhood $\mathcal{U}$ of $\rho_{0}$ in $\operatorname{Hom}(\Gamma, \partial(\Gamma, \mathcal{P}))$ and an open neighborhood $\mathcal{V}^{\prime}$ of the identity in $C(\partial(\Gamma, \mathcal{P}))$ such that for any $\rho \in \mathcal{U} \cap \mathcal{R}_{\mathcal{V}^{\prime}}$, the following hold.
(V1) The representation $\rho$ has the same combinatorics as $\rho_{0}$.
(V2) For any $g \in \Gamma$ satisfying $|g|_{X} \leq D_{1}+D_{2} N$, and any $y, z \in Z$, if $\rho_{0}(g) \overline{W(z)} \subset$ $W(y)$, then $\rho(g) \overline{W(z)} \subset W(y)$.
(V3) For any $q, y \in Z$ with $q$ parabolic, and any $g \in \Gamma$ satisfying $|g|_{X} \leq D_{1}$, if $\rho_{0}(g) \bar{B}_{3 \varepsilon^{\prime}}(q) \subset W(y)$, then $\rho(g) \bar{B}_{3 \varepsilon^{\prime}}(q) \subset W(y)$.
(V4) For every parabolic vertex $q \in Z$ and every edge in $\mathcal{G}$ from $q$ to $y$ labeled by $\alpha$, if $\rho_{0}(\alpha) N_{\varepsilon}(W(y)) \subset B_{\varepsilon^{\prime}}(q)$, then $\rho(\alpha) W(y) \subset B_{3 \varepsilon^{\prime}}(q)$.
Proof. Lemma 6.8 shows that having the same combinatorics is a relatively open condition, thus we can find $\mathcal{U}, \mathcal{V}^{\prime}$ so that Item (V1) holds. Both (V2) and (V3) correspond to open conditions on finitely many elements in $\Gamma$. Thus, we need only demonstrate that by further shrinking $\mathcal{V}^{\prime}$ and $\mathcal{U}$ if needed, we may satisfy (V4)

As in the proof of Lemma 5.3, for each parabolic vertex $q \in Z$, we choose some $t_{q} \in \Gamma$ so that $q=\rho_{0}\left(t_{q}\right) p$ for some $p \in \Pi$. We choose our neighborhood $\mathcal{U}$ of $\rho_{0}$ small enough so that for any $\rho \in \mathcal{U}$ and every parabolic vertex $q \in Z$, we have

$$
\begin{equation*}
\rho\left(t_{q}\right) \rho_{0}\left(t_{q}\right)^{-1} B_{2 \varepsilon^{\prime}}(q) \subset B_{3 \varepsilon^{\prime}}(q) \tag{5}
\end{equation*}
$$

Choose $\mathcal{V}^{\prime}$ sufficiently small so that for any $\phi \in \mathcal{V}^{\prime}$ and every $y \in Z$, we have

$$
\phi(W(y)) \subset N_{\varepsilon}(W(y))
$$

and for every parabolic vertex $q \in Z$, we have

$$
\phi^{-1}\left(\rho_{0}\left(t_{q}\right)^{-1} B_{\varepsilon^{\prime}}(q)\right) \subset \rho_{0}\left(t_{q}\right)^{-1} B_{2 \varepsilon^{\prime}}(q)
$$

Let $\rho \in \mathcal{U} \cap \mathcal{R}_{\mathcal{V}^{\prime}}$. Fix a parabolic vertex $q=t_{q} p \in Z$. Suppose that for some edge $e$ from $q$ to $y$ labeled by $\alpha \in L(q) \subset t_{q} \Gamma_{p}$, we have $\rho_{0}(\alpha) N_{\varepsilon}(W(y)) \subset B_{\varepsilon^{\prime}}(q)$. We may write $\alpha=t_{q} \alpha^{\prime}$ for some $\alpha^{\prime} \in \Gamma_{p}$, so $\rho_{0}\left(\alpha^{\prime}\right) N_{\varepsilon}(W(y)) \subset \rho_{0}\left(t_{q}\right)^{-1} B_{\varepsilon^{\prime}}(q)$.

From this it follows that

$$
\begin{aligned}
\rho\left(\alpha^{\prime}\right) W(y) & \subset \rho\left(\alpha^{\prime}\right) \phi_{p}^{-1} N_{\varepsilon}(W(y)) \\
& =\phi_{p}^{-1}\left(\rho_{0}\left(\alpha^{\prime}\right) N_{\varepsilon}(W(y))\right) \\
& \subset \phi_{p}^{-1}\left(\rho_{0}\left(t_{q}\right)^{-1} B_{\varepsilon^{\prime}}(q)\right) \\
& \subset \rho_{0}\left(t_{q}\right)^{-1} B_{2 \varepsilon^{\prime}}(q) .
\end{aligned}
$$

Putting this together with (5), we conclude that

$$
\rho(\alpha) W(y)=\rho\left(t_{q}\right) \rho\left(\alpha^{\prime}\right) W(y) \subset \rho\left(t_{q}\right) \rho_{0}\left(t_{q}\right)^{-1} B_{2 \varepsilon^{\prime}}(q) \subset B_{3 \varepsilon^{\prime}}(q)
$$

as desired.
6.2. Defining the semi-conjugacy. For the rest of the paper, we fix open sets $\mathcal{U} \subset \operatorname{Hom}(\Gamma, \operatorname{Homeo}(\partial(\Gamma, \mathcal{P})))$ and $\mathcal{V}^{\prime} \subset C(\partial(\Gamma, \mathcal{P}))$ satisfying the conditions of Lemma 6.12. We let $\rho: \Gamma \rightarrow \operatorname{Homeo}(\partial(\Gamma, \mathcal{P}))$ be a representation in $\mathcal{U} \cap \mathcal{R}_{\mathcal{V}^{\prime}}$. We recall from Remark 6.3 that this means that for each $P \in \mathcal{P}$, we fix a semiconjugacy $\phi_{P} \in \mathcal{V}^{\prime}$, such that $\left.\rho\right|_{P}$ is an extension of $\left.\rho_{0}\right|_{P}$ by $\phi_{P}$. In turn this determines semi-conjugacies $\phi_{z}$ extending $\left.\rho\right|_{\Gamma_{z}}$ for each parabolic $z \in \partial(\Gamma, \mathcal{P})$ with stabilizer $\Gamma_{z}$.

Our goal is to show that $\rho$ is semi-conjugate to $\rho_{0}$ via some map $\phi$. We now set about constructing a map $\phi$, and will then show that it is indeed a well-defined semi-conjugacy, and in the neighborhood $\mathcal{V}$ of the identity that was fixed in Section 3.1. The general strategy is to use codings to assign a well-defined closed subset $\Phi(\zeta) \subset \partial(\Gamma, \mathcal{P})$ to each $\zeta \in \partial(\Gamma, \mathcal{P})$, then specify that $\phi$ send $\Phi(\zeta)$ to $\zeta$. To ensure this gives a well-defined continuous map, we need the following lemma.

Lemma 6.13. Let $\zeta$ be a conical limit point in $\partial(\Gamma, \mathcal{P})$, and $s \in \mathcal{S} \cup\{i d\}$. Suppose that $\mathbf{e}=\left(e_{k}\right)_{k \in \mathbb{N}}$ is a strict $\left(\mathcal{G}, \rho_{0}\right)$-coding of $\rho_{0}(s) \zeta$, and $\mathbf{f}=\left(f_{k}\right)_{k \in \mathbb{N}}$ is a strict $\left(\mathcal{G}, \rho_{0}\right)$-coding of $\zeta$; equivalently $(s, \mathbf{f})$ is a generalized $\left(\mathcal{G}, \rho_{0}\right)$-coding of $\rho_{0}(s) \zeta$. Then, for $\alpha_{k}=\mathbf{L a b}\left(e_{k}\right)$ and $\beta_{k}=\mathbf{L a b}\left(f_{k}\right)$, we have

$$
\bigcap_{k=1}^{\infty} \rho\left(\alpha_{1}\right) \cdots \rho\left(\alpha_{k}\right) \overline{W\left(\tau\left(e_{k}\right)\right)}=\rho(s) \bigcap_{k=1}^{\infty} \rho\left(\beta_{1}\right) \cdots \rho\left(\beta_{k}\right) \overline{W\left(\tau\left(f_{k}\right)\right)}
$$

Proof. For each $k \in \mathbb{N}$, write $W^{\mathbf{e}}(k)=W\left(\tau\left(e_{k}\right)\right)$ and $W^{\mathbf{f}}(k)=W\left(\tau\left(f_{k}\right)\right)$. Let $g_{k}$ and $h_{k}$ be the associated quasi-geodesic sequences to the codings $\mathbf{e}=(i d, \mathbf{e})$ and $(s, \mathbf{f})$, respectively (so $\left.h_{0}=s\right)$. Then $h_{k}^{\prime}:=s^{-1} h_{k}=\beta_{1} \cdots \beta_{k}$ is the associated quasi-geodesic sequence to the strict coding $\mathbf{f}$.

We will prove the inclusion

$$
\begin{equation*}
\bigcap_{k=1}^{\infty} \rho\left(g_{k}\right) \overline{W^{\mathbf{e}}(k)} \subseteq \rho(s) \bigcap_{k=1}^{\infty} \rho\left(h_{k}^{\prime}\right) \overline{W^{\mathbf{f}}(k)} \tag{6}
\end{equation*}
$$

Since $\mathcal{S}$ is symmetric, the other inclusion then follows immediately.
Since both intersections in (6) are given by decreasing sequences of sets, it suffices to show that we can find arbitrarily large pairs of indices $L, R$ so that

$$
\rho\left(g_{L}\right) \overline{W^{\mathbf{e}}(L)} \subseteq \rho(s) \rho\left(h_{R}^{\prime}\right) \overline{W^{\mathbf{f}}(R)}
$$

Since both $(i d, \mathbf{e})$ and $(s, \mathbf{f})$ are generalized $\left(\mathcal{G}, \rho_{0}\right)$-codings of the point $\rho_{0}(s) \zeta$, Proposition 5.2 and our choice of constants imply that $(i d, \mathbf{e})$ and $(s, \mathbf{f})$ have the uniform nesting property, with respect to the constants chosen in Convention 6.11. Thus, there exist sequences $n_{k}, m_{k}$ satisfying the properties in Definition 5.1 for the corresponding pair of quasi-geodesic sequences. Let $L$ be one such choice of $n_{k}$, and let $R$ denote $m_{k}$ (for the same $k$ ). Thus, $\left|h_{R}^{-1} g_{L}\right|_{X} \leq D_{1}$.

If uniform nesting with short words holds, we have:

$$
\begin{equation*}
\rho_{0}\left(g_{L+N}\right) \overline{W^{\mathbf{e}}(L+N)} \subset \rho_{0}\left(h_{R}\right) W^{\mathbf{f}}(R) \tag{7}
\end{equation*}
$$

and $\left|\alpha_{L+k}\right|_{X} \leq D_{2}$ for all $k \in \mathbb{N}$.
Let $g_{(L+1, L+N)}=\alpha_{L+1} \cdots \alpha_{L+N}$, so that

$$
g_{L+N}=g_{L} \cdot g_{(L+1, L+N)}
$$

Thus,

$$
\rho_{0}\left(\left(h_{R}\right)^{-1} g_{L}\right) \rho_{0}\left(g_{(L+1, L+N)}\right) \overline{W^{\mathbf{e}}(L+N)} \subset W^{\mathbf{f}}(R)
$$

Since each $\alpha_{L+k}$ has length at most $D_{2}$, we know $\left|g_{(L+1, L+N)}\right|_{X} \leq N D_{2}$. By definition, $\left|h_{R}^{-1} g_{L}\right|_{X} \leq D_{1}$, and therefore $\left|\left(h_{R}\right)^{-1} g_{L} g_{(L+1, L+N)}\right|_{X} \leq D_{1}+N D_{2}$

Thus, by condition (V2) of Lemma 6.12 and our choice of $\mathcal{U}$, we have

$$
\rho\left(g_{L+N}\right) \overline{W^{\mathbf{e}}(L+N)} \subset \rho\left(h_{R}\right) W^{\mathbf{f}}(R)=\rho(s) \rho\left(h_{R}^{\prime}\right) W^{\mathbf{f}}(R)
$$

which is what we needed to show.
If instead we have uniform nesting with long parabolics, then $z_{L}=\tau\left(e_{L}\right)=$ $\iota\left(e_{L+1}\right)$ is parabolic, and we have

$$
\begin{gather*}
\rho_{0}\left(g_{L}\right) \bar{B}_{3 \varepsilon^{\prime}}\left(z_{L}\right) \subset \rho_{0}\left(h_{R}\right) W^{\mathbf{f}}(R)  \tag{8}\\
\rho_{0}\left(\alpha_{L+1}\right) N_{\varepsilon}\left(W^{\mathbf{e}}(L+1)\right) \subset B_{\varepsilon^{\prime}}\left(z_{L}\right) \tag{9}
\end{gather*}
$$

Since $\left|\left(h_{R}\right)^{-1} g_{L}\right|_{X} \leq D_{1}, ~ 88$, together with condition (V3) on the neighborhood $\mathcal{U}$, implies that

$$
\rho\left(g_{L}\right) \bar{B}_{3 \varepsilon^{\prime}}\left(z_{L}\right) \subset \rho\left(h_{R}\right) W^{\mathbf{f}}(R) .
$$

And, our assumption (V4), together with (9), implies that

$$
\rho\left(\alpha_{L+1}\right) W^{\mathbf{e}}(L+1) \subset B_{3 \varepsilon^{\prime}}\left(z_{L}\right)
$$

We can then conclude that

$$
\rho\left(g_{L+1}\right) W^{\mathbf{e}}(L+1) \subset \rho\left(h_{R}\right) W^{\mathbf{f}}(R) .
$$

This means that $\rho\left(g_{L+2}\right) \overline{W^{\mathbf{e}}(L+2)} \subset \rho\left(h_{R}\right) W^{\mathbf{f}}(R)=\rho(s) \rho\left(h_{R}^{\prime}\right) W^{\mathbf{f}}(R)$, and we are done.

Definition 6.14. Define a map $\Phi$ from $\partial(\Gamma, \mathcal{P})$ to the space of closed subsets of $\partial(\Gamma, \mathcal{P})$ as follows:

- If $p \in \partial(\Gamma, \mathcal{P})$ is a conical limit point, choose a strict $\left(\mathcal{G}, \rho_{0}\right)$-coding of $p$ with terminal vertex sequence $\left(z_{k}\right)_{k \in \mathbb{N}}$ and label sequence $\left(\alpha_{k}\right)_{k \in \mathbb{N}}$, and define

$$
\Phi(p)=\bigcap_{k=1}^{\infty} \rho\left(\alpha_{1} \cdots \alpha_{k}\right) \overline{W\left(z_{k}\right)} .
$$

- If $q \in \partial(\Gamma, \mathcal{P})$ is a parabolic point, then we choose some $g \in \Gamma$ so that $q=\rho_{0}(g) p$ for a point $p \in \Pi$. Then define

$$
\Phi(q)=\rho(g) \phi_{p}^{-1}(p) .
$$

Taking $s=i d$ in Lemma 6.13 shows that the map $\Phi$ is well-defined on conical limit points. This lemma also implies that $\Phi\left(\rho_{0}(s) z\right)=\rho(s) \Phi(z)$ for any $s \in \mathcal{S}$ and conical $z$, which means that $\Phi$ is equivariant on conical limit points.

To show $\Phi$ is well-defined on parabolic points, suppose a parabolic point $q$ satisfies $q=\rho_{0}(h) p_{i}=\rho_{0}(g) p_{j}$ for $p_{i}, p_{j} \in \Pi$. Let $P_{i}=\Gamma_{p_{i}}$ and $P_{j}=\Gamma_{p_{j}}$. Then $p_{i}=p_{j}$ and $h \in g P_{i}$, so $\rho(g) \phi_{P_{i}}^{-1}\left(p_{i}\right)=\rho(h) \phi_{P_{j}}^{-1}\left(p_{j}\right)$. The same reasoning shows that in fact $\Phi$ is equivariant on parabolic points: for any $g \in \Gamma$ and parabolic $q \in \partial(\Gamma, \mathcal{P})$, we have $\rho(g) \Phi(q)=\Phi\left(\rho_{0}(g) q\right)$. We record this fact for future use.
Lemma 6.15. The map $\Phi$ is equivariant, in the sense that for any $g \in \Gamma$ and $\zeta \in \partial(\Gamma, \mathcal{P})$, we have

$$
\Phi\left(\rho_{0}(g) \zeta\right)=\rho(g) \Phi(\zeta) .
$$

Our next goal is to show that the sets $\Phi(\zeta)$ partition $\partial(\Gamma, \mathcal{P})$. Towards this, we first observe that the sets $W(z)$ for $z \in Z$ can be used to "approximate" the map $\Phi$, in the following sense.

Lemma 6.16. Let $\zeta \in \partial(\Gamma, \mathcal{P})$, and let $\mathbf{e}$ be a strict $\left(\mathcal{G}, \rho_{0}\right)$-coding for $\zeta$ whose first vertex is $z_{0} \in Z$. Then $\Phi(\zeta) \subset W\left(z_{0}\right)$.
Proof. If $\zeta$ is a conical point, this is immediate from the definition of $\Phi$ and the fact that $\rho$ has the same combinatorics as $\rho_{0}$. Otherwise, we consider a finite $\left(\mathcal{G}, \rho_{0}\right)$-coding $\mathbf{e}$ for the parabolic point $\zeta$, with label sequence $\alpha_{1}, \ldots, \alpha_{n}$ and initial vertex sequence $z_{0}, \ldots, z_{n}$. Then $z_{n}$ is parabolic and $\zeta=\rho_{0}\left(\alpha_{1} \cdots \alpha_{n}\right) z_{n}$, so by equivariance we have $\Phi(\zeta)=\rho\left(\alpha_{1} \cdots \alpha_{n}\right) \Phi\left(z_{n}\right)$. We know $z_{n} \in V\left(z_{n}\right)$ by Property (C5) of our original automaton, so $\Phi\left(z_{n}\right)=\phi_{z_{n}}^{-1}\left(z_{n}\right) \subset V_{\rho}\left(z_{n}\right)$. Then, because $\rho$ has the same combinatorics as $\rho_{0}$, we know $\Phi\left(z_{n}\right) \subset W\left(z_{n}\right)$ (from part (ii) of the definition) and therefore $\Phi(\zeta) \subset W\left(z_{0}\right)$ (from part (iv)).

The endgame of the proof of Theorem 1.1 is identical to that in the case without parabolics, given at the end of Section 4 in MMW22. For convenience, we repeat it below.

Lemma 6.17. For any distinct $a, b \in \partial(\Gamma, \mathcal{P})$, the sets $\Phi(a), \Phi(b)$ are disjoint.
Proof. Given $a \neq b \in \partial(\Gamma, \mathcal{P})$, let $g \in \Gamma$ be such that $d_{\partial}\left(\rho_{0}(g) a, \rho_{0}(g) b\right)>D$, where $D$ is the constant from Definition 2.3. Let $z_{0}$ and $y_{0}$ be the initial vertices of strict $\mathcal{G}$-codings for $\rho_{0}(g) a$ and $\rho_{0}(g) b$, respectively. Then $\rho_{0}(g) a \in W\left(z_{0}\right)$ and $\rho_{0}(g) b \in W\left(y_{0}\right)$. Since each set $W(z)$ has diameter strictly less than $D / 4$, and $d_{\partial}\left(\rho_{0}(g) a, \rho_{0}(g) b\right)>D$, we conclude that $W\left(z_{0}\right) \cap W\left(y_{0}\right)=\emptyset$.

Now Lemma 6.16 states that $\Phi\left(\rho_{0}(g) a\right)=\rho(g) \Phi(a) \subset W\left(z_{0}\right)$, and similarly $\rho(g) \Phi(b) \subset W\left(y_{0}\right)$. Since $W\left(z_{0}\right) \cap W\left(y_{0}\right)=\emptyset$, we also have $\Phi(a) \cap \Phi(b)=\emptyset$.

The fact that every point in $\partial(\Gamma, \mathcal{P})$ has a strict $(\mathcal{G}, \rho)$-coding (Lemma 6.10) ensures that the union of the sets $\Phi(z)$ for $z \in \partial(\Gamma, \mathcal{P})$ is all of $\partial(\Gamma, \mathcal{P})$ and Lemma6.17 ensures that this union is in fact a partition. So, the following definition makes sense and gives a surjective map.
Definition 6.18. Define $\phi: \partial(\Gamma, \mathcal{P}) \rightarrow \partial(\Gamma, \mathcal{P})$ by taking $\phi(x)=y$ if $x \in \Phi(y)$.
We know that $\phi$ is equivariant by Lemma 6.15. so to prove that it is a semiconjugacy lying in our chosen neighborhood $\mathcal{V} \subset C(\partial(\Gamma, \mathcal{P}))$, we just need to prove that it is a continuous map which is $\varepsilon$-close to the identity (see Definition 3.3).

Lemma 6.19. For every $\zeta \in \partial(\Gamma, \mathcal{P})$, we have $d_{\partial}(\zeta, \phi(\zeta))<\varepsilon$.
Proof. Fix $\zeta \in \partial(\Gamma, \mathcal{P})$ and let $\xi=\phi(\zeta)$, so $\zeta \in \Phi(\xi)$. Then by Lemma 6.16. if $\mathbf{e}$ is a $\left(\mathcal{G} \rho_{0}\right)$-coding for $\xi$ with initial vertex $z_{0}$, we have both $\xi \in W\left(z_{0}\right)$ and $\Phi(\xi) \subset W\left(z_{0}\right)$, hence $\zeta \in W\left(z_{0}\right)$. Since $\operatorname{diam}\left(W\left(z_{0}\right)\right)<\varepsilon$ by property (C1), the result follows.

Lemma 6.20. The map $\phi$ is continuous.
Proof. Fix $\zeta \in \partial(\Gamma, \mathcal{P})$. By the previous lemma we know that $d_{\partial}(\zeta, \phi(\zeta))<\varepsilon$. To show continuity at $\zeta$ we will use equivariance and the convergence action of $\Gamma$ on $\partial(\Gamma, \mathcal{P})$. Suppose $\zeta_{n} \rightarrow \zeta$, but along some subsequence we have $\phi\left(\zeta_{n}\right) \rightarrow \xi \neq \phi(\zeta)$. By equivariance of $\phi$, we may assume without loss of generality (after applying some $g \in \Gamma$ ) that $d_{\partial}(\xi, \phi(\zeta))>D$, where $D$ is the constant from Definition 2.3. On the other hand, by the triangle inequality we have

$$
d_{\partial}\left(\phi\left(\zeta_{n}\right), \phi(\zeta)\right) \leq d_{\partial}\left(\phi\left(\zeta_{n}\right), \zeta_{n}\right)+d_{\partial}\left(\zeta_{n}, \zeta\right)+d_{\partial}(\zeta, \phi(\zeta))<3 \varepsilon
$$

provided that $n$ is sufficiently large. Then $d_{\partial}\left(\xi, \phi\left(\zeta_{n}\right)\right)>D-3 \varepsilon>\varepsilon$, which gives a contradiction.

This completes the demonstration that $\phi$ is a semiconjugacy satisfying the properties of Theorem 1.1, and concludes the proof.

## Appendix A. Uniform nesting for automata

The purpose of this appendix is to prove a uniform nesting property for finitestate automata which "code points" with respect to a $\Gamma$-action on some Hausdorff space $M$. Special cases of this result were originally stated as Lemma 3.8 and Corollary 3.11 in MMW22. We use essentially the same proof as in that paper to show the general statement (Lemma A. 3 below).

We start with some general set-up. Let $G$ be any group acting by homeomorphisms on a Hausdorff space $M$. As in Section 4 of this paper, for any edge $e$ in a directed graph, we let $\iota(e)$ and $\tau(e)$ respectively denote the initial and terminal vertices of $e$.
Definition A.1. A finitary point coder $\mathcal{Q}$ for the action $G \curvearrowright M$ consists of
(1) A finite collection $\mathcal{W}(\mathcal{Q})$ of open sets of $M$.
(2) A finite collection $F(\mathcal{Q})$ of elements of $G$.
(3) A finite directed graph, with each vertex $v$ labeled by an open set $W(v) \in$ $\mathcal{W}(\mathcal{Q})$, and each edge $e$ labeled by an element $\mathbf{L a b}(e) \in F(\mathcal{Q})$, satisfying the following conditions:
(a) Whenever there is an edge from $z_{1}$ to $z_{2}$ labeled by $\alpha$, there is an inclusion $\alpha \overline{W\left(z_{2}\right)} \subset W\left(z_{1}\right)$.
(b) Whenever $\mathbf{e}=\left(e_{k}\right)_{k \in \mathbb{N}}$ is an infinite edge path with terminal vertex sequence $\tau\left(e_{k}\right)=z_{k}$ and edge labels $\alpha_{k}=\mathbf{L a b}\left(e_{k}\right)$, the sequence of sets $\left(\alpha_{1} \cdots \alpha_{n} W\left(z_{n}\right)\right)_{n \in \mathbb{N}}$ is a system of neighborhoods for a point $p \in M$. Such an edge path is called a strict $\mathcal{Q}$-coding of the point $p$.

If $\mathbf{e}=\left(e_{k}\right)_{k \in \mathbb{N}}$ is a strict $\mathcal{Q}$-coding of $p$ with labels $\mathbf{L a b}\left(e_{k}\right)=\alpha_{k}$ and terminal vertices $v_{k}=\tau\left(e_{k}\right)$, it follows immediately that the intersection

$$
\bigcap_{n \in \mathbb{N}} \alpha_{1} \cdots \alpha_{n} W\left(v_{n}\right)
$$

is equal to $\{p\}$. If $M$ is metrizable and every set $W \in \mathcal{W}(\mathcal{Q})$ has compact closure (which is the case for all of our applications), then the converse also holds: if $\mathbf{e}=$ $\left(e_{k}\right)_{k \in \mathbb{N}}$ is an edge path with label sequence $\left(\alpha_{k}\right)_{k \in \mathbb{N}}$, and $\bigcap_{n \in \mathbb{N}} \alpha_{1} \cdots \alpha_{n} W\left(\tau\left(e_{n}\right)\right)=$ $\{p\}$, then $\mathbf{e}$ is a $\mathcal{Q}$-coding of $p$.
Definition A.2. Let $\mathcal{Q}$ be a finitary point coder. A generalized $\mathcal{Q}$-coding is a pair $\left(g_{0}, \mathbf{e}\right)$, where $g_{0} \in G$ and $\mathbf{e}$ is a strict $\mathcal{Q}$-coding. If $\mathbf{e}$ is a strict coding of $p \in M$, then we say that the generalized coding $\left(g_{0}, \mathbf{e}\right)$ codes the point $g_{0} p \in M$.

The label sequence and initial/terminal vertex sequences of a generalized coding $\left(g_{0}, \mathbf{e}\right)$ are defined to be the same as the corresponding sequences for the strict coding $\mathbf{e}$. If $\left(\alpha_{k}\right)_{k \in \mathbb{N}}$ is the label sequence for a generalized coding $\left(g_{0}, \mathbf{e}\right)$, then the path sequence associated to the coding is the sequence $\left(g_{k}\right)_{k \in \mathbb{N} \cup\{0\}}$ in $G$ defined by

$$
g_{k}:=g_{0} \cdot \alpha_{1} \cdots \alpha_{k}
$$

We prove the following:
Lemma A. 3 (Uniform nesting for finitary point coders). For any finite subset $F \subset G$ and any finitary point coders $\mathcal{Q}, \mathcal{Q}^{\prime}$, there is a number $N=N\left(\mathcal{Q}, \mathcal{Q}^{\prime}, F\right)$ satisfying the following. Suppose that $\left(g_{0}, \mathbf{c}\right)$ is a generalized $\mathcal{Q}^{\prime}$-coding of $p$ with path sequence $\left(g_{k}\right)_{k \in \mathbb{N} \cup\{0\}}$ and terminal vertex sequence $\left(z_{k}\right)_{k \in \mathbb{N}}$, and $\left(h_{0}, \mathbf{d}\right)$ is a generalized $\mathcal{Q}$-coding of $p$ with path sequence $\left(h_{k}\right)_{k \in \mathbb{N} \cup\{0\}}$ and terminal vertex sequence $\left(y_{k}\right)_{k \in \mathbb{N}}$. Then, for any indices $m, n \in \mathbb{N}$ satisfying $g_{n}^{-1} h_{m} \in F$, we have

$$
\begin{equation*}
g_{n+N} \overline{W\left(z_{n+N}\right)} \subset h_{m} W\left(y_{m}\right) \tag{10}
\end{equation*}
$$

Proof. Fix a finite set $F \subset G$ and finitary point coders $\mathcal{Q}, \mathcal{Q}^{\prime}$. The proof is by contradiction, so we therefore assume we have a sequence of natural numbers $N$ tending to $\infty$ so that for each $N$ in the sequence, there is a point $p^{N} \in M$, a generalized $\mathcal{Q}^{\prime}$-coding $\left(g_{0}^{(N)}, \mathbf{c}^{(N)}\right)$ of $p^{(N)}$ with path sequence $\left(g_{k}^{(N)}\right)_{k \in \mathbb{N} \cup\{0\}}$ and
terminal vertex sequence $\left(z_{k}^{(N)}\right)_{k \in \mathbb{N}}$, a generalized $\mathcal{Q}-\operatorname{coding}\left(h_{0}^{(N)}, \mathbf{d}^{(N)}\right)$ of $p^{(N)}$ with path sequence $\left(h_{k}^{(N)}\right)_{k \in \mathbb{N} \cup\{0\}}$ and terminal vertex sequence $\left(y_{k}^{(N)}\right)_{k \in \mathbb{N}}$, and indices $m_{N}, n_{N} \in \mathbb{N}$ so that $\left(g_{n_{N}}^{(N)}\right)^{-1} h_{m_{N}}^{(N)} \in F$, but the inclusion 10) fails. That is, for each $N$, we have

$$
\begin{equation*}
g_{n_{N}+N}^{(N)} \overline{W\left(z_{n_{N}+N}^{(N)}\right)} \not \subset h_{m_{N}}^{(N)} W\left(y_{m_{N}}^{(N)}\right) . \tag{11}
\end{equation*}
$$

We immediately pass to a subsequence so that

$$
\begin{equation*}
\left(g_{n_{N}}^{(N)}\right)^{-1} h_{m_{N}}^{(N)} \text { is constant, equal to } f \in F \tag{f}
\end{equation*}
$$

We further refine our subsequence so the following three conditions are satisfied.
(z) The sets $W\left(z_{n_{N}+N}^{(N)}\right)$ are constant, equal to some $W \in \mathcal{W}\left(\mathcal{Q}^{\prime}\right)$.
(y) The sets $W\left(y_{m_{N}}^{(N)}\right)$ are constant, equal to some $U \in \mathcal{W}(\mathcal{Q})$.
(*) The sets $\left(h_{m_{N}}^{(N)}\right)^{-1} h_{m_{N}+1}^{(N)} W\left(y_{m_{N}+1}^{(N)}\right)$ are constant, equal to some $U^{\prime}$.
The first two are possible because the sets $\mathcal{W}\left(\mathcal{Q}^{\prime}\right)$ and $\mathcal{W}(\mathcal{Q})$ are finite; the third also uses the fact that each $\mathbf{d}^{(N)}$ is a (strict) $\mathcal{Q}$-coding, so the elements $\left(h_{m_{N}}^{(N)}\right)^{-1} h_{m_{N}+1}^{(N)}$ lie in the finite set $F(\mathcal{Q})$. A key property we will use at the end of the proof is that

$$
\begin{equation*}
\bar{U}^{\prime} \subset U \tag{12}
\end{equation*}
$$

The fact that $\mathbf{c}^{(N)}$ is a $\mathcal{Q}^{\prime}$-coding implies that for each $k \geq 1$, we have $g_{k}^{(N)}=$ $g_{k-1}^{(N)} \alpha$ for some $\alpha$ chosen from the finite set $F\left(\mathcal{Q}^{\prime}\right)$. For $N$ in our subsequence, we can multiply each side of (11) on the left by $\left(g_{n_{N}}^{(N)}\right)^{-1}$ and apply condition (f) to obtain

$$
\begin{equation*}
\alpha_{1}^{(N)} \cdots \alpha_{N}^{(N)} \bar{W} \not \subset f U, \tag{13}
\end{equation*}
$$

where $\alpha_{k}^{(N)}:=\left(g_{n_{N}+k-1}^{(N)}\right)^{-1} g_{n_{N}+k}^{(N)}$ is the label of an edge $e_{k}^{(N)}$ in $\mathcal{Q}^{\prime}$.
For each $N$ we consider the infinite edge path $\gamma^{(N)}$ in $\mathcal{Q}^{\prime}$ given by

$$
\gamma^{(N)}:=\left(e_{1}^{(N)}, e_{2}^{(N)}, \ldots\right)
$$

We note that $\gamma^{(N)}$ is a strict $\mathcal{Q}^{\prime}$-coding, coding the point $\left(g_{n_{N}}^{(N)}\right)^{-1} p^{N}$.
Passing to a subsequence $\{N(j)\}_{j \in \mathbb{N}}$ one final time, we obtain a sequence of strict $\mathcal{Q}^{\prime}$-codings $\left\{\gamma^{(N(j))}\right\}_{j \in \mathbb{N}}$ so that for all $l \geq j$, the initial subsegment of length $j$ of the $\mathcal{Q}^{\prime}$-coding $\gamma^{N(l)}$ is independent of $l$. In particular this subsequence of codings converges to a strict $\mathcal{Q}^{\prime}$-coding

$$
\gamma^{\infty}=\left(e_{1}^{\infty}, e_{2}^{\infty}, \ldots\right)
$$

with edge labels $\alpha_{k}^{\infty}:=\mathbf{L a b}\left(e_{k}^{\infty}\right)$. By property (3b) of $\mathcal{Q}^{\prime}$, this coding determines a unique point $p^{\infty} \in M$.

For our subsequence $N(j)$, the non-containment in takes the form

$$
\alpha_{1}^{(N(j))} \cdots \alpha_{N(j)}^{(N(j))} \bar{W} \not \subset f U .
$$

We may assume that $N(j)>j$ for all $j$, so we can rewrite this as

$$
\left(\alpha_{1}^{\infty} \cdots \alpha_{j}^{\infty}\right)\left(\alpha_{j+1}^{(N(j))} \cdots \alpha_{N(j)}^{(N(j))}\right) \bar{W} \not \subset f U .
$$

By the nesting property of codings we have

$$
\left(\alpha_{1}^{\infty} \cdots \alpha_{j}^{\infty}\right)\left(\alpha_{j+1}^{(N(j))} \cdots \alpha_{N(j)}^{(N(j))}\right) \bar{W} \subset\left(\alpha_{1}^{\infty} \cdots \alpha_{j}^{\infty}\right) W_{j}^{\infty}
$$

so we must therefore have

$$
\begin{equation*}
\left(\alpha_{1}^{\infty} \cdots \alpha_{j}^{\infty}\right) W_{j}^{\infty} \not \subset f U \tag{14}
\end{equation*}
$$

Since $\gamma^{\infty}$ is a coding for $p^{\infty}$, the sets on the left hand side of give a nested basis of neighborhoods of $p^{\infty}$ and so we conclude

$$
\begin{equation*}
p^{\infty} \notin f U \tag{15}
\end{equation*}
$$

On the other hand, for each $N, \gamma^{(N)}$ is a coding for $\left(g_{n_{N}}^{(N)}\right)^{-1} p^{N}$. Thus for each $j$ we have

$$
\begin{gathered}
\left(g_{\left.n_{N(j)}^{(N(j))}\right)^{-1} p^{N(j)} \in \alpha_{1}^{(N(j))} \cdots \alpha_{j}^{(N(j))} W_{j}^{(N(j))}}^{=\alpha_{1}^{\infty} \cdots \alpha_{j}^{\infty} W_{j}^{\infty}} .\right.
\end{gathered}
$$

As before this last sequence of sets is a nested neighborhood basis for $p^{\infty}$ and thus

$$
\lim _{j \rightarrow \infty}\left(g_{n_{N(j)}}^{(N(j))}\right)^{-1} p^{N(j)}=p^{\infty}
$$

We also know that, for any $N$,

$$
\begin{equation*}
\left(g_{n_{N}}^{(N)}\right)^{-1} p^{N} \in\left(g_{n_{N}}^{(N)}\right)^{-1} h_{m_{N}+1}^{(N)} \overline{W\left(y_{m_{N}+1}^{(N)}\right)} \tag{16}
\end{equation*}
$$

since $\mathbf{d}^{(N)}$ also codes $p^{N}$. By our assumptions (f) and (*) on our chosen subsequence, the right-hand side of 16 is always equal to a constant $f U^{\prime}$. But we have just seen that a subsequence of the left-hand side converges to $p^{\infty}$, so we must have $p^{\infty} \in f \overline{U^{\prime}}$. Because of 12 this implies

$$
p^{\infty} \in f U
$$

contradicting 15).

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